Pursuit of Low-dimensional Structures in High-dimensional (Visual) Data

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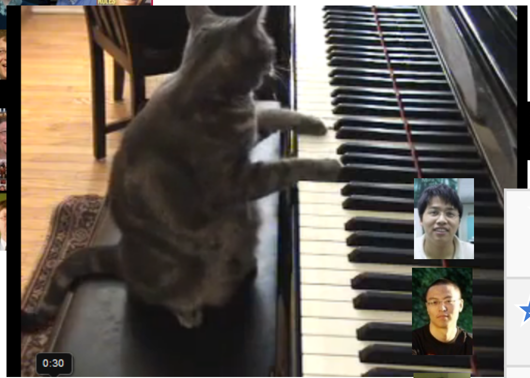
CONTEXT – *Data increasingly massive, high-dimensional…*

Images

⇓➢ ***1M pixels***

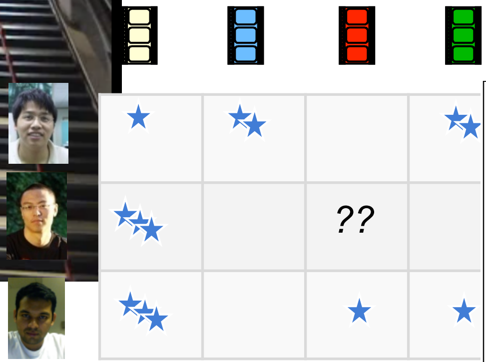
Compression
De-noising
Super-resolution
Recognition…



Videos

⇓➢ ***1B voxels***

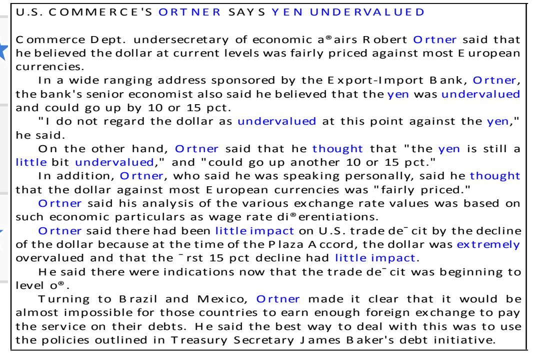
Streaming
Tracking
Stabilization…



User data

⇓➢ ***1B users***

Clustering
Classification
Collaborative filtering…



U.S. COMMERCE'S ORTNER SAYS YEN UNDERVALUED

Commerce Dept. undersecretary of economic a®airs Robert Ortner said that he believed the dollar at current levels was fairly priced against most European currencies.

In a wide ranging address sponsored by the Export-Import Bank, Ortner, the bank's senior economist also said he believed that the yen was undervalued and could go up by 10 or 15 pct.

"I do not regard the dollar as undervalued at this point against the yen," he said.

On the other hand, Ortner said that he thought that "the yen is still a little bit undervalued," and "could go up another 10 or 15 pct."

In addition, Ortner, who said he was speaking personally, said he thought that the dollar against most European currencies was "fairly priced."

Ortner said his analysis of the various exchange rate values was based on such economic particulars as wage rate di®erentiations.

Ortner said there had been little impact on U.S. trade de¯cit by the decline of the dollar because at the time of the Plaza Accord, the dollar was extremely overvalued and that the ¯rst 15 pct decline had little impact.

He said there were indications now that the trade de¯cit was beginning to level o®.

Turning to Brazil and Mexico, Ortner made it clear that it would be almost impossible for those countries to earn enough foreign exchange to pay the service on their debts. He said the best way to deal with this was to use the policies outlined in Treasury Secretary James Baker's debt initiative.

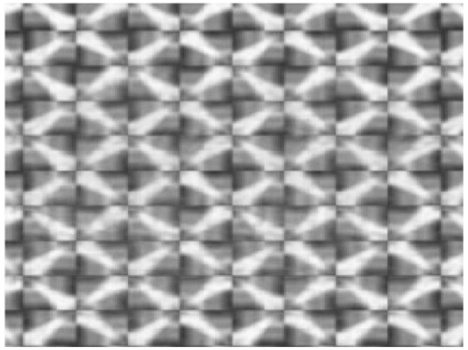
Web data

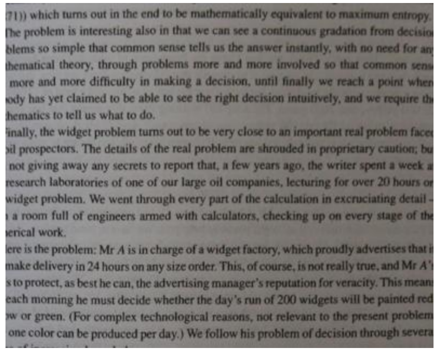
⇓➢ ***100B webpages***

Indexing
Ranking
Search…

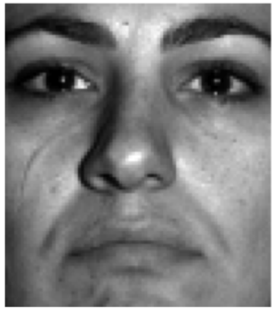
How to extract low-dim structures from such high-dim data?

CONTEXT – *Low dimensional structures in visual data*

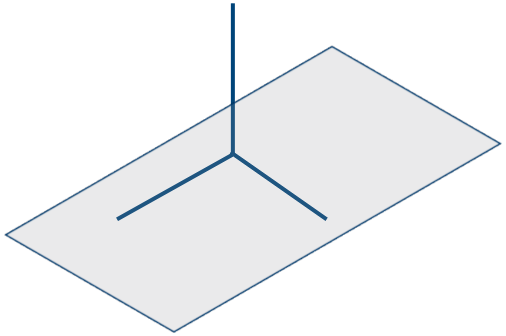




71)) which turns out in the end to be mathematically equivalent to maximum entropy.
The problem is interesting also in that we can see a continuous gradation from decisio
blems so simple that common sense tells us the answer instantly, with no need for an
thematical theory, through problems more and more involved so that common sens
more and more difficulty in making a decision, until finally we reach a point wher
ody has yet claimed to be able to see the right decision intuitively, and we require th
hematics to tell us what to do.
inally, the widget problem turns out to be very close to an important real problem face
il prospectors. The details of the real problem are shrouded in proprietary caution; bu
not giving away any secrets to report that, a few years ago, the writer spent a week a
research laboratories of one of our large oil companies, lecturing for over 20 hours o
widget problem. We went through every part of the calculation in excruciating detail –
a room full of engineers armed with calculators, checking up on every stage of the
erical work.
ere is the problem: Mr *A* is in charge of a widget factory, which proudly advertises that i
make delivery in 24 hours on any size order. This, of course, is not really true, and Mr *A*'
s to protect, as best he can, the advertising manager's reputation for veracity. This mean
each morning he must decide whether the day's run of 200 widgets will be painted red
w or green. (For complex technological reasons, not relevant to the present problem
one color can be produced per day.) We follow his problem of decision through severa



Visual data exhibit ***low-dimensional structures*** due to rich ***local*** regularities, ***global*** symmetries, ***repetitive*** patterns, or ***redundant*** sampling.



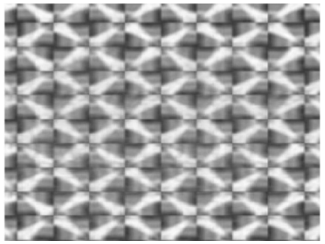
CONTEXT – *PCA: Fitting Data with a Low-dim. Subspace*

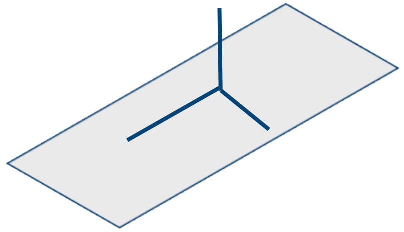
If we view the data (image) as a matrix

$$A = [\mathbf{a}_1 \mid \cdots \mid \mathbf{a}_n] \in \mathbb{R}^{m \times n}$$

then

$$r \doteq \operatorname{rank}(A) \ll m.$$



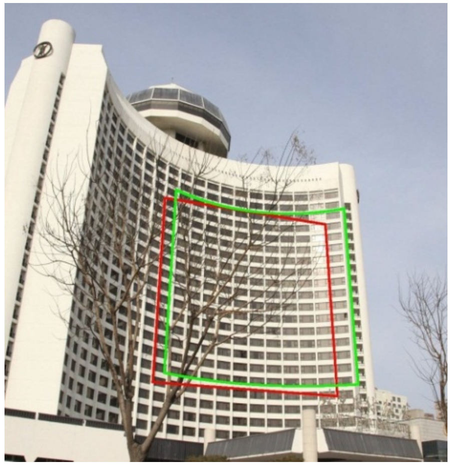


Principal Component Analysis (PCA) via singular value decomposition (SVD):

- Optimal estimate of A under iid Gaussian noise $D = A + Z$
- Efficient and scalable computation
- Fundamental statistical tool, with huge impact in image processing, vision, web search, bioinformatics…

But… **PCA breaks down under even a single corrupted observation.**

CONTEXT – *But life is not so easy…*



*Real application data often contain **missing observations**, **corruptions,** or subject to unknown **deformation or misalignment.***

Classical methods (e.g., PCA, least square regression) break down…

Everything old …

*A **long and rich history** of robust estimation with error correction and missing data imputation:*

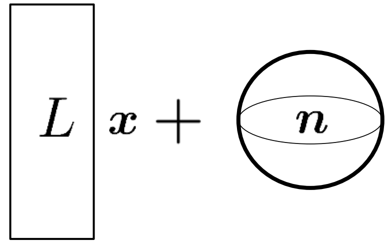
R. J. Boscovich. *De calculo probailitatum que respondent diversis valoribus summe errorum post plures observationes … , before 1756*

A. Legendre. *Nouvelles methodes pour la determination des orbites des cometes*, 1806

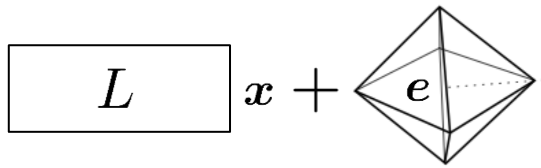
C. Gauss. *Theory of motion of heavenly bodies, 1809*

A. Beurling. *Sur les integrales de Fourier absolument convergentes et leur application a une transformation functionelle*, 1938

B. Logan. *Properties of High-Pass Signals*, 1965



over-determined
\+ dense, Gaussian

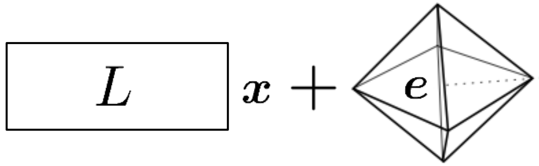


underdetermined
\+ sparse, Laplacian

… is new again

*Today, robust estimation in high dimension is more **urgent** and increasingly **better understood.***

Theory – high-dimensional geometry & statistics, measure concentration, combinatorics, coding theory…



underdetermined
+ sparse, Laplacian

$$\downarrow$$

$$\min \|\boldsymbol{x}\|_1 + \|\boldsymbol{e}\|_1$$

$$\downarrow$$

Algorithms – large scale convex optimization, geometric convergence rate, parallel and distributed computing …

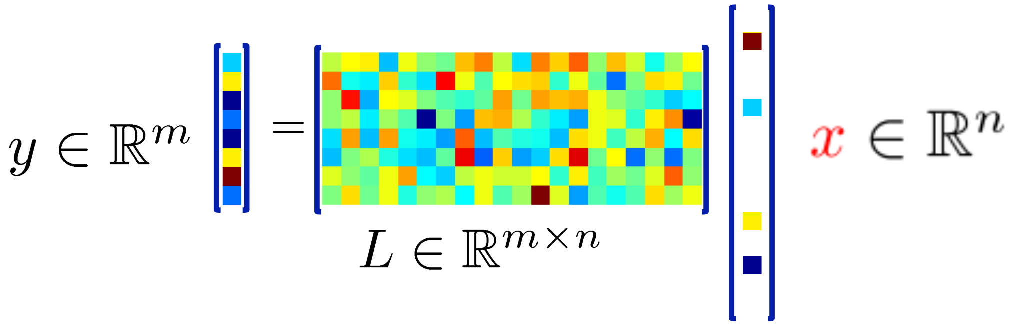
Applications – big data driven methods, sensing and hashing, denoising, superresolution, MRI, bioinformatics, image classification, recognition …

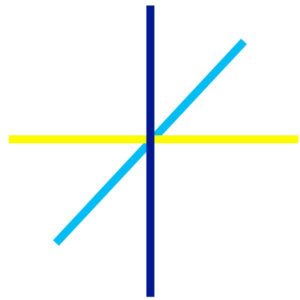
Tukey, Bickel, Huber, Hampel, Tibishirani, Donoho, … Candes and Tao 2004 …

and many more I will mention later…

CONTEXT – *Recent related progress*

Sparse recovery: Given $y = Lx_0$, $L \in \mathbb{R}^{m \times n}$, $m \ll n$, recover x_0.





Impossible in general ($m \ll n$)

Well-posed if x_0 is structured *(sparse),* but still **NP-hard**

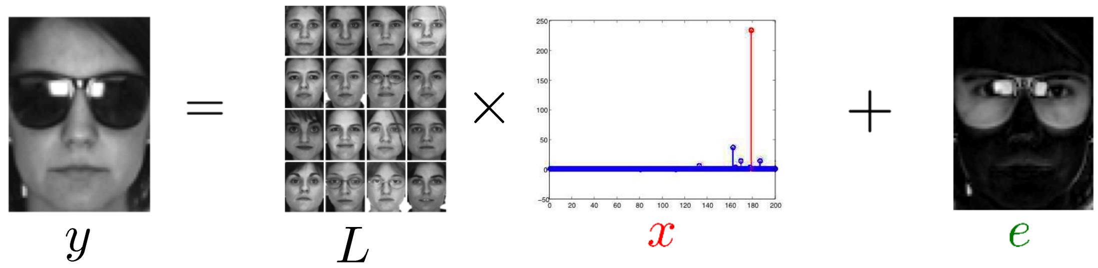
Tractable via convex optimization: $\min \|x\|_1 \text{ s.t. } y = Lx$

… if L is "nice" *(random, incoherent, RIP)*

Hugely active area: *Donoho+Huo '01, Elad+Bruckstein '03, Candès+Tao '04,'05, Tropp '04, '06, Donoho '04, Fuchs '05, Zhao+Yu '06, Meinshausen+Buhlmann '06, Wainwright '09, Donoho+Tanner '09 … and many others*

CONTEXT – *Recent related progress*

Robust recovery: Given $y = Lx_0 + e_0$, $L \in \mathbb{R}^{m \times n}$, $m \ll n$, recover x_0 and e_0.



Impossible in general ($m \ll n + m$)

Well-posed if x_0 is *sparse,* errors e_0 not too dense, but still **NP-hard**

Tractable: via convex optimization: $\min \|x\|_1 + \|e\|_1 \text{ s.t. } y = Lx + e$

… if L is "nice" *(cross and bouquet)*

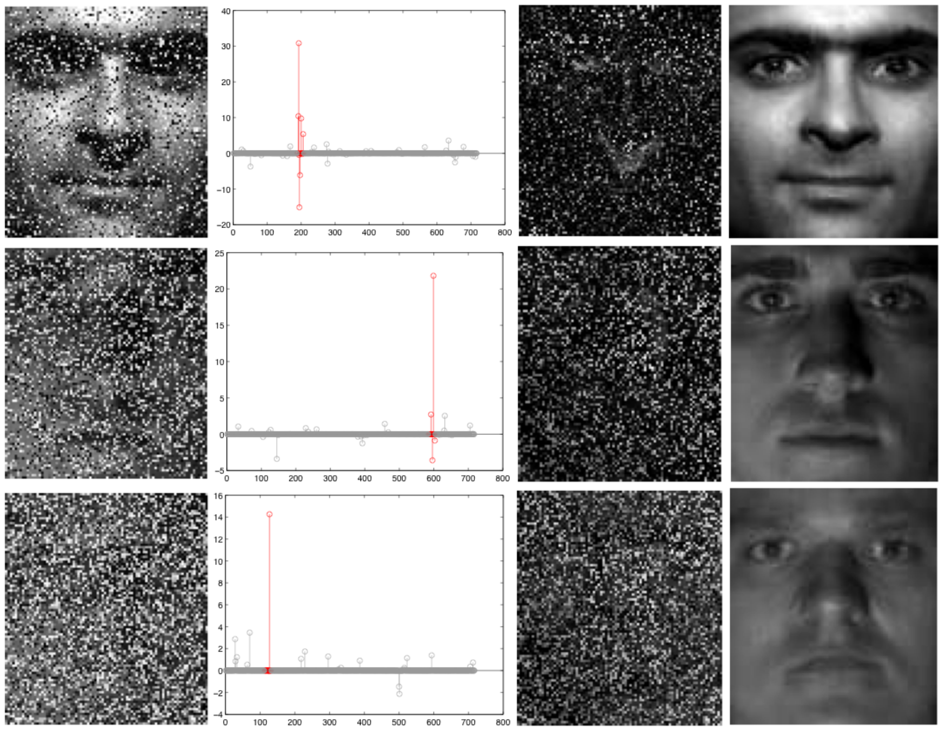
Hugely active area*: Candès+Tao '05, Wright+Ma '10, Nguyen+Tran '11, Li '11, also Zhang, Yang, Huang'11, etc…*

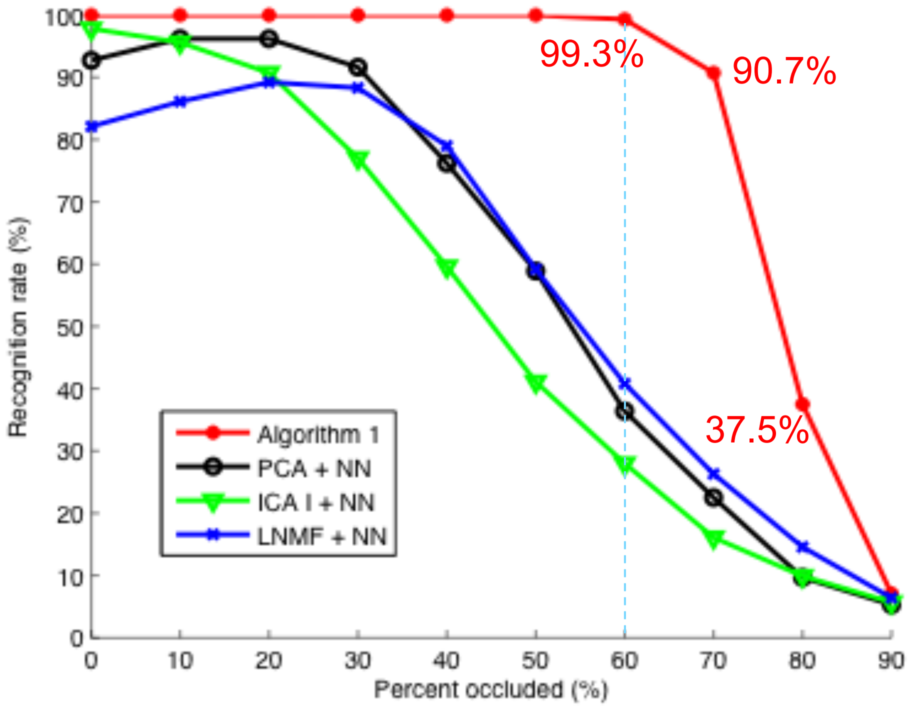
EXPERIMENTS – *Varying Level of Random Corruption*

Extended Yale B Database
(38 subjects)

Training: subsets 1 and 2 (717 images)
Testing: subset 3 (453 images)

$\boldsymbol{y}$ $\quad \widehat{\boldsymbol{x}}_1 \quad \widehat{\boldsymbol{e}}_1 \quad \widehat{\boldsymbol{y}}_0 = A\widehat{\boldsymbol{x}}_1$

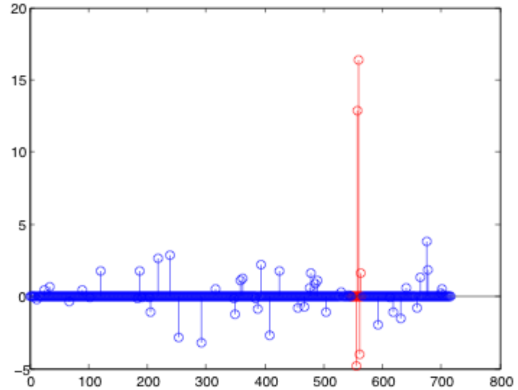




Wright, Yang, Ganesh, Sastry, and Ma. *Robust Face Recognition via Sparse Representation*, TPAMI 2009

ROBUST RECOGNITION - *L_1 versus L_2 Solution*

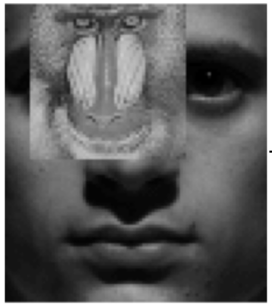
$$\hat{\boldsymbol{x}}_1 = \arg\min \ \|\boldsymbol{x}\|_1 + \|\boldsymbol{e}\|_1.$$



$\hat{\boldsymbol{e}}_1$

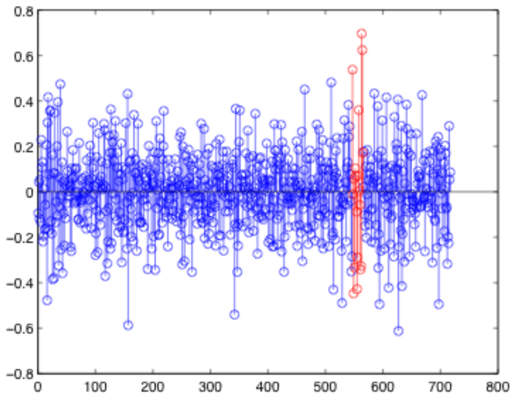
$\hat{\boldsymbol{y}}_0 = A\hat{\boldsymbol{x}}_1$

Input: $\boldsymbol{y} \in \mathbb{R}^D$



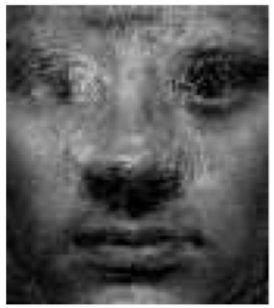
$$\boldsymbol{y} = A\boldsymbol{x} + \boldsymbol{e}$$

$$\hat{\boldsymbol{x}}_2 = \arg\min_{\boldsymbol{x}} \ \|\boldsymbol{y} - A\boldsymbol{x}\|_2.$$



$\hat{\boldsymbol{e}}_2$

$\hat{\boldsymbol{y}}_0 = A\hat{\boldsymbol{x}}_2$



EXPERIMENTS – *Extension to Single Gallery Image Case*

$$y = Lx + Ab + e$$

A: a common dictionary for intraclass variabilities: illumination, expression, and pose.

x, b, e are sparse

FERET Dataset

General training: 1,002 images of 429 people

Gallery training: 1,196 images of 1,196 people

Probe sets:

fb (1,195, expression), fc (194, lighting), dup1 (722, different time), dup2 (234, a year)

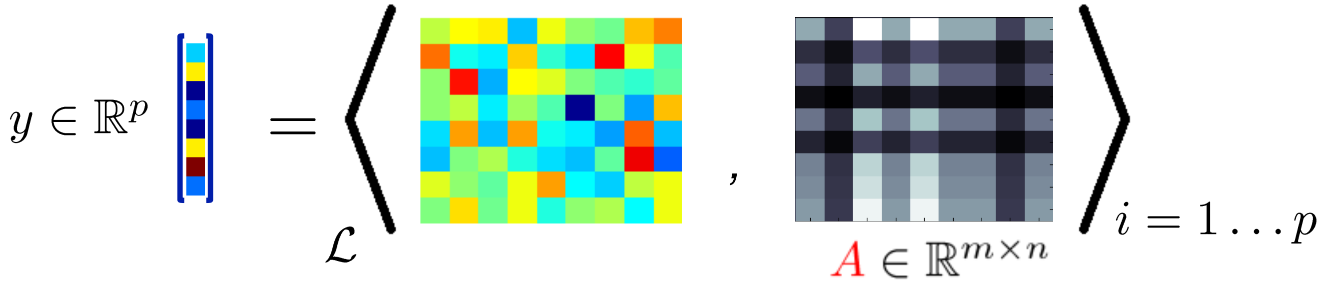
TABLE 3

Comparative Recognition Rates of SRC and ESRC on the FERET Database Using the FERET'96 Testing Protocol

	Feature	Dsampled Image	Pixel-Rfaces	Pixel	Gabor-Rfaces	Gabor	LBP-Rfaces	LBP
Probe set	Dim	24×24	540	16384	540	10240	540	15104
fb	SRC	86.4	82.4	85.3	89.5	92.8	91.5	96.7
	ESRC	94.8(+8.4)	91.5(+9.1)	92.8(+7.5)	94.1(+4.6)	**97.3**(+4.5)	95.2(+3.7)	**97.3**(+0.6)
fc	SRC	69.6	75.8	76.3	96.4	97.4	72.7	93.3
	ESRC	67.5(−2.1)	78.9(+3.1)	79.4(+3.1)	96.9(+0.5)	**99.0**(+1.6)	71.1(−1.6)	95.4(+2.1)
dup1	SRC	62.7	60.9	63.7	63.0	72.7	75.2	87.7
	ESRC	75.6(+12.9)	73.1(+12.2)	77.0(+13.3)	73.5(+10.5)	85.0(+12.3)	81.0(+5.8)	**93.8**(+6.1)
dup2	SRC	52.6	53.0	55.6	70.1	76.5	69.7	83.8
	ESRC	62.4(+9.8)	59.8(+6.8)	66.2(+10.6)	72.6(+2.5)	85.9(+9.4)	71.4(+1.7)	**92.3**(+8.5)

CONTEXT – *Recent related progress*

Low-rank recovery: Given $y = \mathcal{L}[A_0]$, $\mathcal{L} : \mathbb{R}^{m\times n} \to \mathbb{R}^p$, recover A_0.



Impossible in general ($p \ll mn$)

Well-posed if A_0 is structured *(low-rank),* but still **NP-hard**

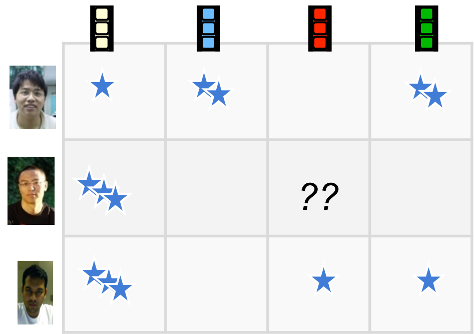
Tractable via convex optimization: $\min \|A\|_* \text{ s.t. } y = \mathcal{L}(A)$

… if $\mathcal{L}$ is “nice” *(random, rank-RIP)*

Hugely active area: *Recht+Fazel+Parillo ‘07, Candès+Plan ’10, Mohan+Fazel ‘10, Recht+Xu+Hassibi ’11, Chandrasekaran+Recht+Parillo+Willsky ‘11, Negahban+Wainwright ’11 …*

CONTEXT – *Recent related progress*

Matrix completion: Given $y = \mathcal{P}_\Omega[A_0]$, $\Omega \subset [m] \times [n]$, recover A_0.



$A \in \mathbb{R}^{m \times n}$

Impossible in general ($|\Omega| \ll mn$)

Well-posed if A_0 is structured *(low-rank),* but still **NP-hard**

Tractable via convex optimization: $\min \|A\|_* \text{ s.t. } y = \mathcal{P}_Q(A)$

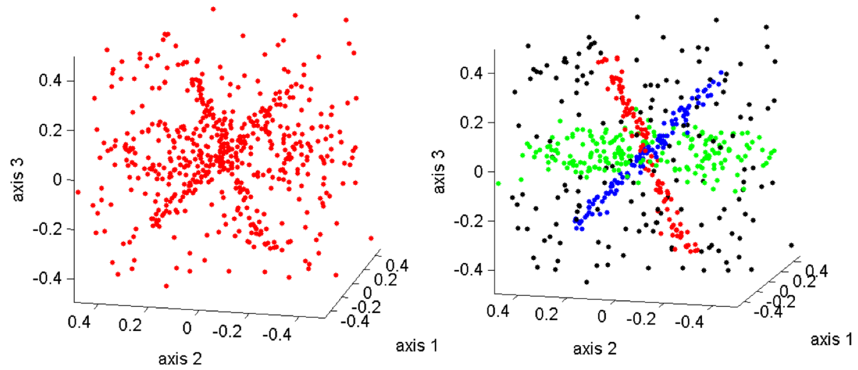
… if Ω is “nice” *(random subset) ...*

… and A_0 interacts “nicely” with $\mathcal{P}_\Omega$ (A_0 *incoherent – not “spiky”*).

Hugely active area: *Candès+Recht ‘08, Keshevan+Oh+Montonari ‘09, Candès+Tao ‘09, Gross ‘10, Recht ‘10, Negahban+Wainwright ‘10*

CONTEXT – *Recent related progress*

Subspace Clustering: Given $Y : [y_1, \ldots, y_n] \subset S_1, \ldots, S_k$, recover the subspaces.



Y (with outliers)

Impossible in general (solutions highly ambiguous)

Well-posed if $\{S_i\}$ are few and structured *(low-dim),* but still **combinatorial**

Tractable via convex optimization: $\min \|X\|_\diamond + \|E\|_1$ s.t. $Y = YX + E$.

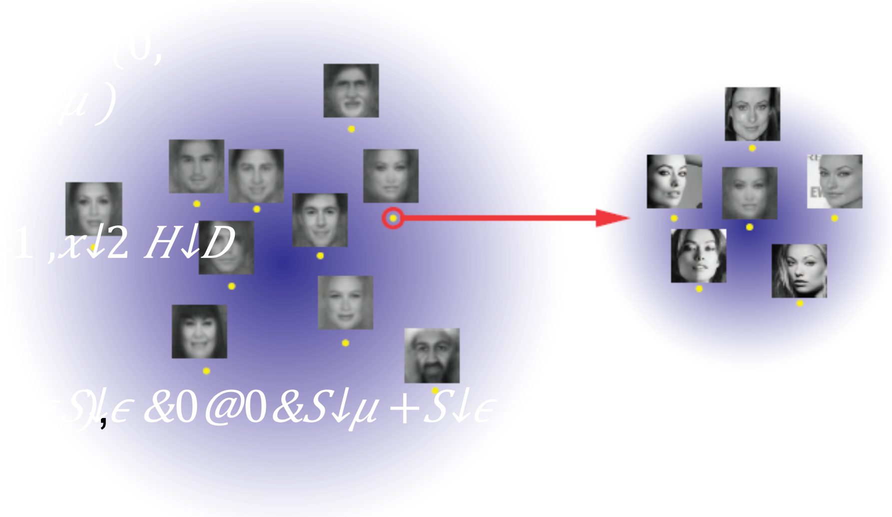
… for random samples Y

… X and *outliers* E *are sparse (or low-rank, column-wise sparse).*

Hugely active area: *Rao, Tron, Ma, Vidal'08, Elhamifar and Vidal'2010, Liu, Lin, Sun, Yan, Ma et. al.' 2011, Soltanolkotabi and Candes' 2011*

CONTEXT – *Recent related progress*

Bayesian Face Verification:



Impossible to learn the covariance matrices in general case.

Well-posed if they are structured *(low-dim),* but still **high-dimensional**

Tractable via **rank-regularized** optimization:

Hugely active area: non-convex, Bayesian sparsity or low-rank regularization, *Wipf '2004, 2011, 2012…*

Bayesian Face Revisited: A Joint Formulation, Chen et. al., ECCV 2012.

CONTEXT – *Recent related progress*

- LFW dataset: 13,000 images, 2,000+ subjects
- Training and testing using the same
  LFW unconstraint protocol
- Using the same open source feature*

Methods	Accuracy
Bayesian (MSRA)	**87.5%**
PLDA(2012)	86.2%
LDML(2009)	83.2%
DML-eig(2012)	81.3%

[*http://lear.inrialpes.fr/people/guillaumin/data.php](http://lear.inrialpes.fr/people/guillaumin/data.php)

Prince, S., Li, P., Fu, Y., Mohammed, U., Elder, J.: **Probabilistic models for inference about identity**. PAMI **34** (2012) 144–157

CONTEXT – *Recent related progress*

MSRA WDRef

- 99,773 images
- 2,995 subjects
- Wide & Deep

Methods	Accuracy
Bayesian (MSRA)	**92.4%**
face.com (2011)	**91.3%**
combined PLDA, funneled & aligned(2012)	90.07%
Associate-Predict(2011) *our previous work*	90.57%
Combined multishot, aligned(2010)	89.50%
LDML-MkNN, funneled(2009)	87.50%
Attribute and Simile classifiers(2009)	85.29%

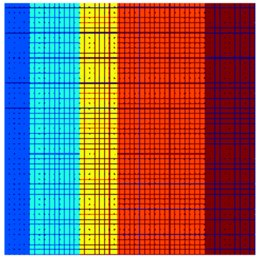
Billions of data

3D face model

Bayesian Face Revisited: A Joint Formulation, Chen et. al., ECCV 2012.

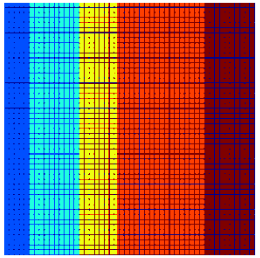
CONTEXT – *Low-dimensional Models*

The data should be ***low-dimensional (low-rank)****:*



$$A = [\mathbf{a}_1 \mid \cdots \mid \mathbf{a}_n] \in \mathbb{R}^{m \times n}, \qquad \mathrm{rank}(A) \ll m.$$

CONTEXT – *Low-dimensional Models*



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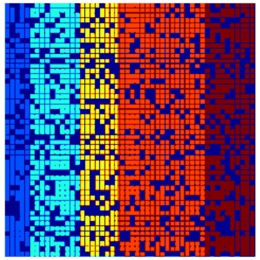

*… but some of the observations are **grossly corrupted**:*

$$A + E, \qquad |E_{ij}|$$

E_{ij} arbitrarily large, but most are zero.

CONTEXT – *Low-dimensional Models*

*The data should be **low-dimensional**:*

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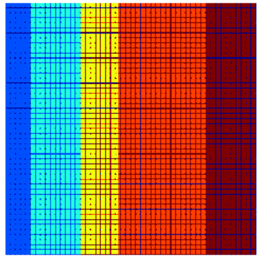

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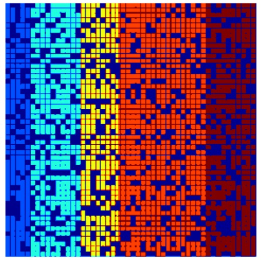
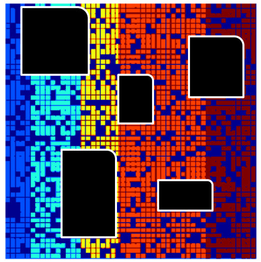


*… and some of them can be **missing** too:*

$$D = \mathcal{P}_\Omega[A + E],$$

$\Omega \subset [m] \times [n]$ the set of observed entries.



CONTEXT – *Low-dimensional Models*

The data should be ***low-dimensional****:*

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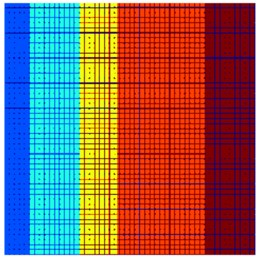

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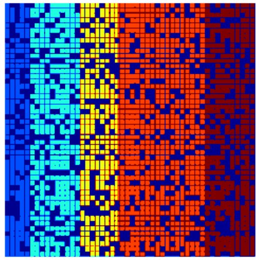
$$A + E, \qquad |E_{ij}|$$

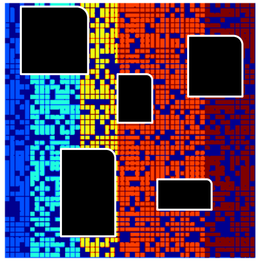
E_{ij} arbitrarily large, but most are zero.



… and some of them can be ***missing*** *too:*

$$D = \mathcal{P}_\Omega[A + E],$$

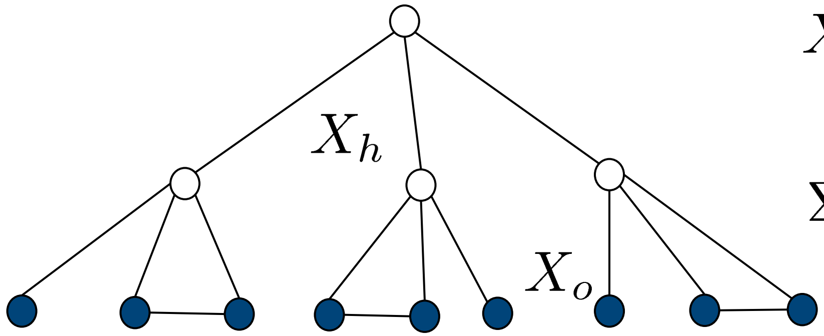
$\Omega \subset [m] \times [n]$ the set of observed entries.



… special cases of a more general problem:

$$D = \mathcal{L}_1(A) + \mathcal{L}_2(E) + Z \qquad A, E \text{ either sparse or low-rank}$$

CONTEXT: Learning Graphical Models



$$X = (X_o, X_h) \sim \mathcal{N}(0, \Sigma)$$

$$\Sigma = \begin{bmatrix} \Sigma_o & \Sigma_{oh} \\ \Sigma_{ho} & \Sigma_h \end{bmatrix} \Rightarrow \Sigma^{-1} = \begin{bmatrix} J_o & J_{oh} \\ J_{ho} & J_h \end{bmatrix}$$

$X_i,\ X_j$ cond. indep. given other variables $\Leftrightarrow$ $\left(\Sigma^{-1}\right)_{ij} = 0$

Separation Principle:

$$\begin{array}{ccccc} \Sigma_o^{-1} & = & J_o & - & J_{oh} J_h^{-1} J_{ho} \\ \text{observed} & = & \text{sparse} & + & \text{low-rank} \end{array}$$

- sparse pattern → conditional (in)dependence
- rank of second component → number of hidden variables

THIS TALK

Given observations $D = \mathcal{P}_Q[A + E + Z]$, *with*

A *low-rank,*

E *sparse,*

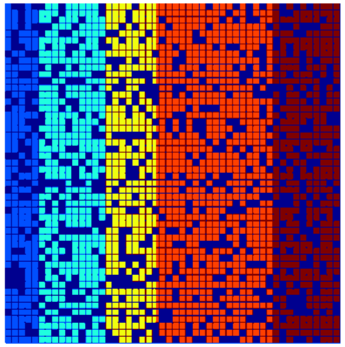
Z *small, dense noise,*

recover a good estimate of A *and* E*.*

- ❑ **Theory and Algorithm**
  - **Provably Correct and Tractable Solution**
  - **Provably Optimal and Efficient Algorithms**
- ❑ **Potential Applications**
  - **Visual Data (Restoration, Reconstruction, Recognition)**
  - **Other Data**
- ❑ **Conclusions**

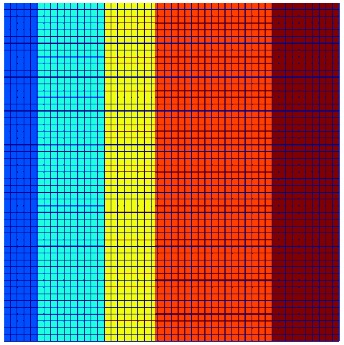
ROBUST PCA – *Problem Formulation*

D - observation



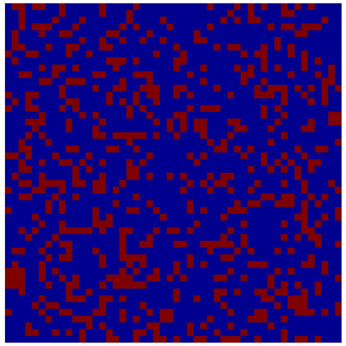
=

A_0 – low-rank



+

E_0 – sparse



Problem: Given $D = \underbrace{A_0}_{\text{Low-rank component}} + \underbrace{E_0}_{\text{Sparse component (gross errors)}}$, recover A_0 and E_0 .

Numerous approaches in the literature:

- Multivariate trimming [Gnanadesikan and Kettering '72]
- Power Factorization [Wieber'70s]
- Random sampling [Fischler and Bolles '81]
- Alternating minimization [Shum & Ikeuchi'96, Ke and Kanade '03]
- Influence functions [de la Torre and Black '03]

Key question: ***can guarantee correctness with an efficient algorithm?***

ROBUST PCA – *Convex Surrogates for Sparsity and Rank*

Seek the lowest-rank A that agrees with the data up to some sparse error E:

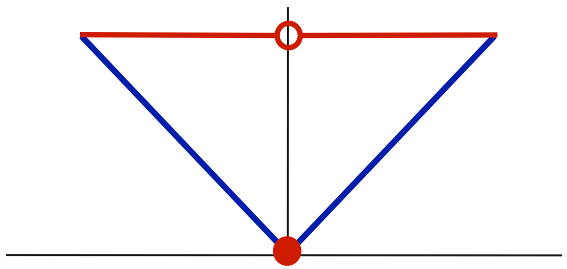
$$\min \ \mathrm{rank}(A) + \gamma \|E\|_0 \quad \mathrm{subj} \quad A + E = D.$$

But INTRACTABLE! Relax with convex surrogates:

$$\|E\|_0 = \#\{E_{ij} \neq 0\} \quad \to \quad \|E\|_1 = \textstyle\sum_{ij} |E_{ij}|.$$ L_1 norm

$$\mathrm{rank}(A) = \#\{\sigma_i(A) \neq 0\} \quad \to \quad \|A\|_* = \textstyle\sum_i \sigma_i(A).$$ Nuclear norm

Convex envelope over $B_{2,2} \times B_{1,\infty}$



ROBUST PCA – *By Convex Optimization*

Seek the lowest-rank A that agrees with the data up to some sparse error E:

$$\min \ \operatorname{rank}(A) + \gamma \|E\|_0 \quad \text{subj} \quad A + E = D.$$

But INTRACTABLE! Relax with convex surrogates:

$$\|E\|_0 = \#\{E_{ij} \neq 0\} \quad \rightarrow \quad \|E\|_1 = \textstyle\sum_{ij} |E_{ij}|.$$ L_1 norm

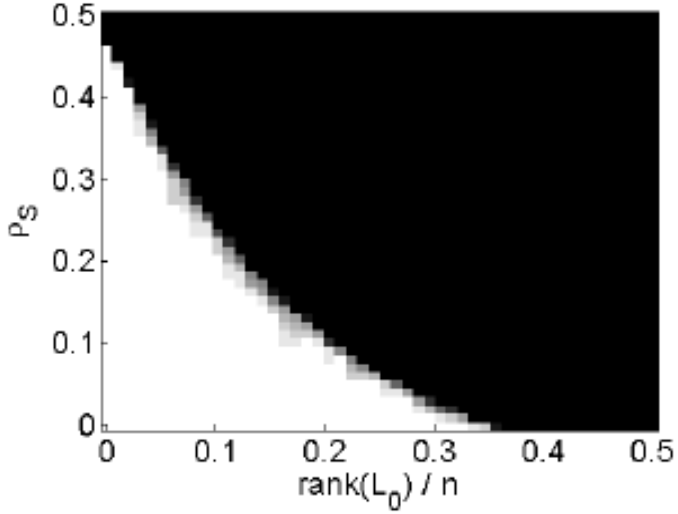
$$\operatorname{rank}(A) = \#\{\sigma_i(A) \neq 0\} \quad \rightarrow \quad \|A\|_* = \textstyle\sum_i \sigma_i(A).$$ Nuclear norm

$$\min \ \|A\|_* + \lambda \|E\|_1 \quad \text{subj} \quad A + E = D.$$

Semidefinite program, solvable in polynomial time

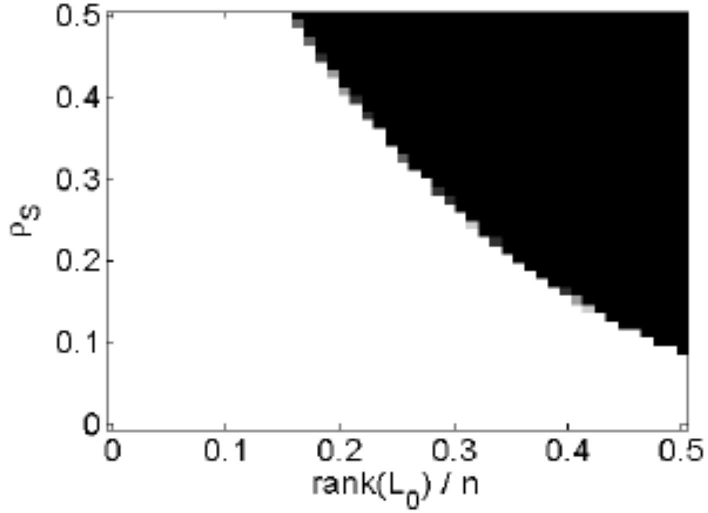
ROBUST PCA – *When the Convex Program Works?*

$D = A + E$



Robust PCA, Random Signs

$D = \mathcal{P}_\Omega[A]$



Matrix Completion

White regions are instances with perfect recovery.

Correct recovery when A is indeed **low-rank** and E is indeed **sparse**?

MAIN THEORY – *Exact Solution by Convex Optimization*

Theorem 1 (Principal Component Pursuit). *If* $A_0 \in \mathbb{R}^{m\times n}$, $m \geq n$ *has rank*

$$m$$

Non-adaptive weight factor

and E_0 *has Bernoulli support with error probability* $\rho \leq \rho_s^\star$, *then with very high probability*

$$(A_0, E_0) \;=\; \arg\min \|A\|_* + \frac{1}{\sqrt{m}}\|E\|_1 \quad \text{subj} \quad A + E = A_0 + E_0,$$

and the minimizer is unique.

GREAT NEWS: *"Convex optimization recovers almost any matrix of rank* $O\left(\frac{m}{\log^2 n}\right)$ *from errors corrupting* $O(mn)$ *of the observations!"*

Candes, Li, Ma, and Wright, Journal of the ACM, May 2011.

MAIN THEORY – *Corrupted, Incomplete Matrix*

$$D = \mathcal{P}_\Omega[\ A_0 \ + \ E_0 \ ], \qquad \Omega \sim \mathrm{uni}\binom{[m]\times[n]}{mn}$$

Theorem 2 (Matrix Completion and Recovery). *If* $A_0, E_0 \in \mathbb{R}^{m\times n}, m \geq n$*, with*

$$\mathrm{rank}(A_0) \ \leq \ C\,\frac{n}{\mu\log^2(m)}, \quad \textit{and} \quad \|E_0\|_0 \ \leq \ \rho^\star mn,$$

and we observe only a random subset of size

$$|\Omega| = mn/10$$

entries, then with very high probability, solving the convex program

$$\min \|A\|_* + \tfrac{1}{\sqrt{m}}\|E\|_1 \quad \text{subj} \quad P_\Omega[A+E] = D,$$

uniquely recovers (A_0, E_0)*.*

MAIN THEORY – *With Dense Errors and Noise*

Theorem 3 (Dense Error Correction). *If A_0 has rank $r \leq \rho_r \frac{m}{\mu^2 \log^2(n)}$ and E_0 has random signs and Bernoulli support with error probability $\rho < 1$, then with very high probability*

$$(A_0, E_0) = \arg\min \|A\|_* + \lambda \|E\|_1 \quad \text{subj} \quad A + E = A_0 + E_0,$$

and the minimizer is unique.

Theorem 4 (Robust PCA with Noise). *Given $D = A_0 + E_0 + Z$ for any $\|Z\|_F \leq \eta$, if A_0 has rank $r \leq \rho_r \frac{m}{\mu^2 \log^2(n)}$ and E_0 has Bernoulli support with error probability $\rho \leq \rho_s^\star$, then with very high probability*

$$(\hat{A}, \hat{E}) = \arg\min \|A\|_* + \frac{1}{\sqrt{m}} \|E\|_1 \quad \text{subj} \quad \|D - A - E\| \leq \eta,$$

sastisfies $\|(\hat{A}, \hat{E}) - (A_0, E_0)\| \leq C\eta$ for some constant $C > 0$.

FIRST RESULTS OF THIS TYPE

Example: *for* $D = A_0 + E_0$,

Previous Best Result *[Chandrasekharan, Parrilo, Wilsky'11]:*

Deterministic error models, success when $\|E\|_0 \leq Cm^{1.5}/r^{.5} \log m.$

Does not guarantee to correct nonzero fractions of errors, even with *r* = 1.

FIRST RESULTS OF THIS TYPE

Example: *for* $D = A_0 + E_0$,

Previous Best Result *[Chandrasekharan et. al.]:*

Success when $\|E\|_0 \le C m^{1.5} / r^{.5} \log m.$

Does not guarantee to correct nonzero fractions of errors, even with $r = 1$.

Our results:

Corrects nonzero fractions of errors, even with $r = O\left(m / \log^2 n\right)$,

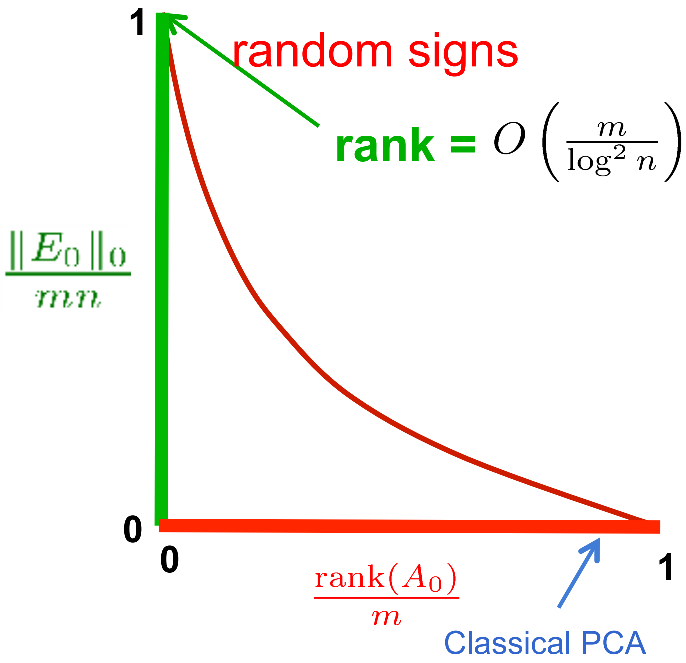
Considers **corruption**, **missing elements** *and* **noise**: $\mathcal{P}_\Omega[\ A_0 + E_0 + Z\ ]$

BIG PICTURE – *Landscape of Theoretical Guarantees*

What people have known so far in the past 3-4 years:

Matrix Recovery (RPCA)

$$D = A + E$$

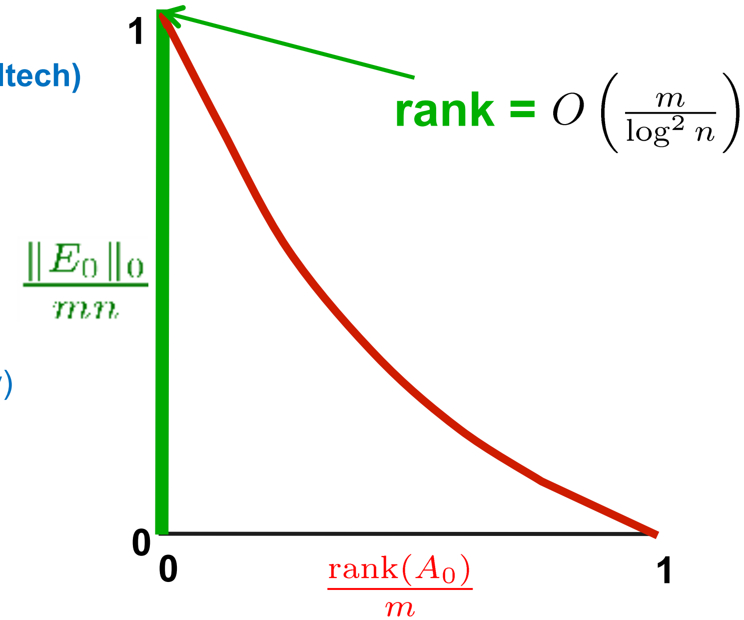


D. Gross
E. Candes (Stanford)
B. Recht (UC Berkeley)
J. Wright (Columbia)
J. Tropp (Caltech)
Chandrasekharan (Caltech)

B. Hassibi (Caltech)
P. Parrilo (MIT)
A. Willsky (MIT)
B. Hastie (Stanford)
C. Montanari (Stanford)
M. Jordan (Berkeley)
M. Wainwright (Berkeley)
B. Yu (Berkeley)
A. Singer (Princeton)
T. Tao (UCLA)
S. Osher (UCLA)
O. Milenkovic (UIUC)
Y. Bresler (UIUC)
Y. Ma (UIUC)
M. Fazel (U Wash.)

Matrix Completion

$$D = \mathcal{P}_\Omega[A]$$

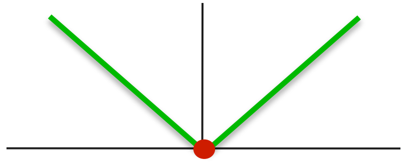


This phase transition landscape has been precisely understood! (Tropp et. al.)

ALGORITHMS – *Are scalable solutions possible?*

Seemingly BAD NEWS: Our optimization problem

$$\min \ \|A\|_* + \lambda \|E\|_1 \quad \text{subj} \quad A + E = D.$$



is high-dimensional and non-smooth.

Convergence rate of solving a generic convex program: $\min_x f(x)$

Second-order Newton method, # of iterations: $O(\log(1/\varepsilon))$, but not scalable!

First-order methods depend strongly on the smoothness of f:

Function class $\mathcal{F}$	Suboptimality $f(\boldsymbol{x}_k) - f(\boldsymbol{x}^*)$
smooth — f convex, differentiable $\|\nabla f(\boldsymbol{x}) - \nabla f(\boldsymbol{x}')\| \le L\|\boldsymbol{x} - \boldsymbol{x}'\|$	$\frac{CL\|\boldsymbol{x}_0 - \boldsymbol{x}^*\|^2}{k^2} = \Theta\left(\frac{1}{k^2}\right)$
smooth + structured nonsmooth: $F = f + g$; f, g convex, $\|\nabla f(\boldsymbol{x}) - \nabla f(\boldsymbol{x}')\| \le L\|\boldsymbol{x} - \boldsymbol{x}'\|$	$\frac{CL\|\boldsymbol{x}_0 - \boldsymbol{x}^*\|^2}{k^2} = \Theta\left(\frac{1}{k^2}\right)$
nonsmooth — f convex $\|f(\boldsymbol{x}) - f(\boldsymbol{x}')\| \le M\|\boldsymbol{x} - \boldsymbol{x}'\|$	$\frac{CM\|\boldsymbol{x}_0 - \boldsymbol{x}^*\|}{\sqrt{k}} = \Theta\left(\frac{1}{\sqrt{k}}\right)$

Y. Nesterov, Introductory Lectures on Convex Optimization: A Basic Course, 2003.

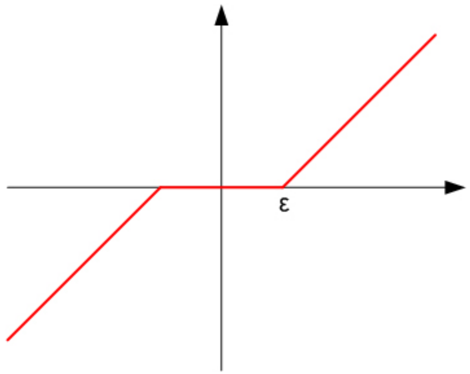
ALGORITHMS – *Why are scalable solutions possible?*

GOOD NEWS: The objective function has special structures

$$\min \ \|A\|_* + \lambda \|E\|_1 \ \ \text{subj} \ \ A + E = D.$$

KEY OBSERVATION: Simple solutions for the proximal operations, given by soft-thresholding the entries or singular values of the matrix, respectively.

$$\begin{aligned} \mathcal{S}_\varepsilon(Q) &= \operatorname{argmin}_X \varepsilon\|X\|_1 + \frac{1}{2}\|X - Q\|_F^2 \\ \mathcal{D}_\varepsilon(Q) &= \operatorname{argmin}_X \varepsilon\|X\|_* + \frac{1}{2}\|X - Q\|_F^2 \end{aligned}$$



For composite functions $F = f + g$, with f smooth,
***if g has an efficient proximal operator**, we achieve*
the same (optimal) rate as if F was smooth.

ALGORITHMS – *Evolution of scalable algorithms*

GOOD NEWS: Scalable first-order gradient-descent algorithms:

- Proximal Gradient [Osher, Mao, Dong, Yin '09,Wright et. al.'09, Cai et. al.'09].
- Accelerated Proximal Gradient [Nesterov '83, Beck and Teboulle '09]:
- Augmented Lagrange Multiplier [Hestenes '69, Powell '69]:
- Alternating Direction Method of Multipliers [Gabay and Mercier '76].

A scalable algorithm: alternating direction method (ADMoM) for ALM:

$$l(A, E, Y) = \|A\|_* + \lambda\|E\|_1 + \langle Y, D - A - E\rangle + \frac{\mu}{2}\|D - A - E\|_F^2$$

$$\textit{repeat}\begin{cases} A_{k+1} = \mathcal{D}_{\mu_k^{-1}}(D - E_k + Y_k/\mu_k), & \textit{Shrink singular values} \\ E_{k+1} = \mathcal{S}_{\lambda\mu_k^{-1}}(D - A_{k+1} + Y_k/\mu_k), & \textit{Shrink absolute values} \\ Y_{k+1} = Y_k + \mu_k(D - A_{k+1} - E_{k+1}). & \end{cases}$$

Cost of each iteration is a classical PCA, i.e. a (partial) SVD.

ALGORITHMS – *Evolution of fast algorithms (around 2009)*

For a 1000x1000 matrix of rank 50, with 10% (100,000) entries randomly corrupted: $\min \|A\|_* + \lambda\|E\|_1 \quad \text{subj} \quad A + E = D.$

Algorithms	Accuracy	Rank	||E||_0	# iterations	time (sec)
IT	5.99e-006	50	101,268	8,550	119,370.3
DUAL	8.65e-006	50	100,024	822	1,855.4
APG	5.85e-006	50	100,347	134	1,468.9
APG_P	5.91e-006	50	100,347	134	82.7
EALM_P	2.07e-007	50	100,014	34	37.5
IALM_P	3.83e-007	50	99,996	23	11.8

10,000 times speedup!

***Provably Robust PCA* at only a constant factor (≈20) more computation than conventional PCA!**

GREAT NEWS: Geometric convergence for gradient algorithms!

f restricted strong convex: $O(\log(1/\varepsilon))$ [Agarwal, Negahban, Wainwright, NIPS 2010]

f smooth, ∇f Lipschitz: $O(\varepsilon^{-1/2})$

f differentiable: $O(\varepsilon^{-1})$

f non-smooth: $O(\varepsilon^{-2})$

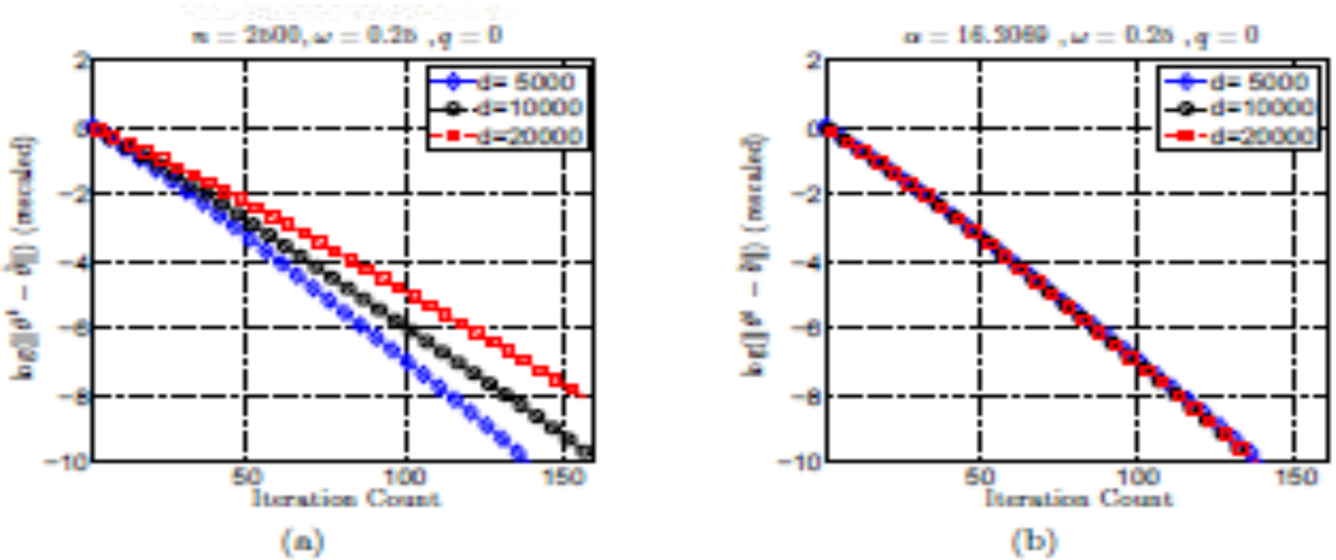


Figure 1. Convergence rates of projected gradient descent in application to Lasso programs (ℓ_1-constrained least-squares). Each panel shows the log optimization error $\log \|\theta^t - \widehat{\theta}\|$ versus the iteration number t. Panel (a) shows three curves, corresponding to dimensions $d \in \{5000, 10000, 20000\}$, sparsity $s = \lceil \sqrt{d} \rceil$, and all with the same sample size $n = 2500$. All cases show geometric convergence, but the rate for larger problems becomes progressively slower. (b) For an appropriately rescaled sample size ($\alpha = \frac{n}{s \log d}$), all three convergence rates should be roughly the same, as predicted by the theory.

ALGORITHMS – *Recap and Conclusions*

Key challenges of **nonsmoothness** and **scale** can be mitigated by using **special structure** in sparse and low-rank optimization problems:

Efficient proximity operators $\Rightarrow$ *proximal gradient methods*

Separable objectives $\Rightarrow$ *alternating directions methods*

Efficient **moderate-accuracy solutions** for **very large problems**.

Special tricks can further improve specific cases (factorization for low-rank)

Techniques in this literature apply quite broadly.

Extremely useful tools for creative problem formulation / solution.

Fundamental **theory** guiding engineering **practice**:

What are the basic principles and limitations?
What specific structure in my problem can allow me to do better?

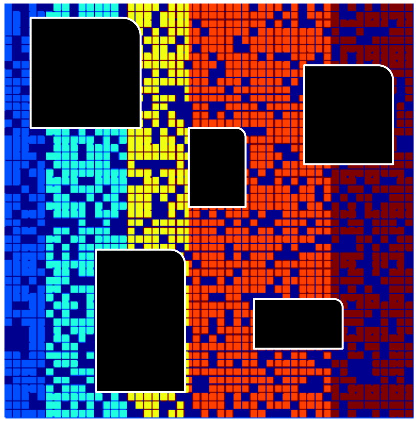
APPLICATIONS

- **Repairing Images and Videos**
  - Image Repairing, Background Extraction, Street Panorama
- **Reconstructing 3D Geometry**
  - Shape from Texture, Featureless 3D Reconstruction
- **Registering Multiple Images**
  - Multiple Image Alignment, Video Stabilization
- **Recognizing Objects**
  - Faces, Texts, etc
- **Other Data and Applications**

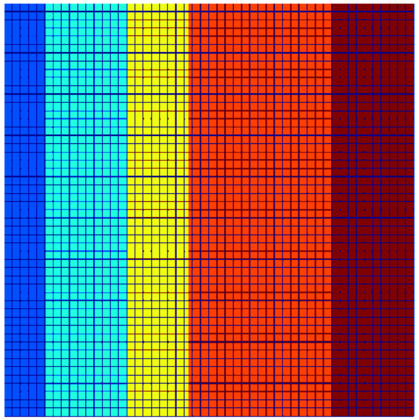
Implications: Highly Compressive Sensing of Structured Information!

Recover low-dimensional structures from a fraction of missing measurements with structured support.

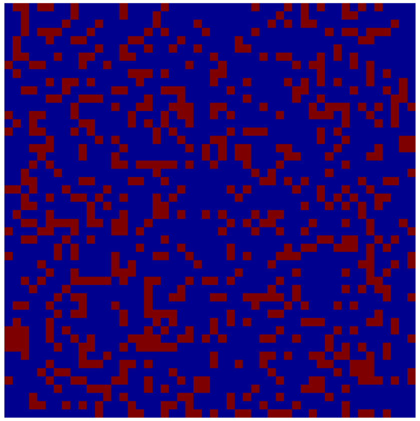
compressive samples



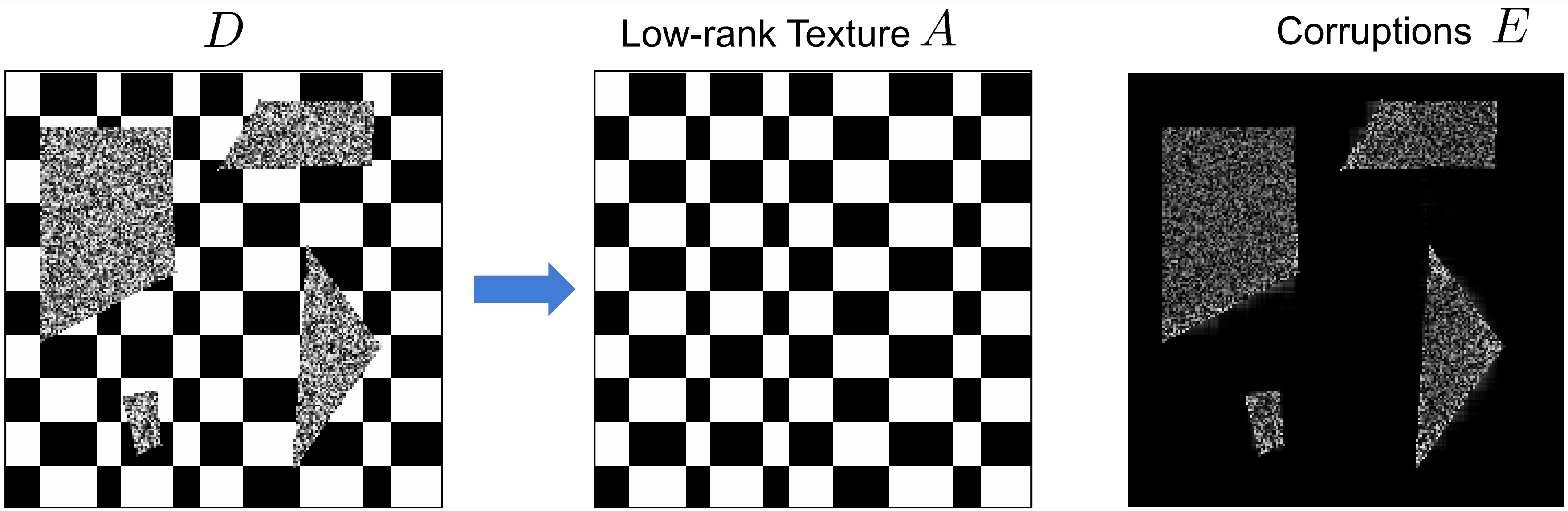
Low-rank Structures

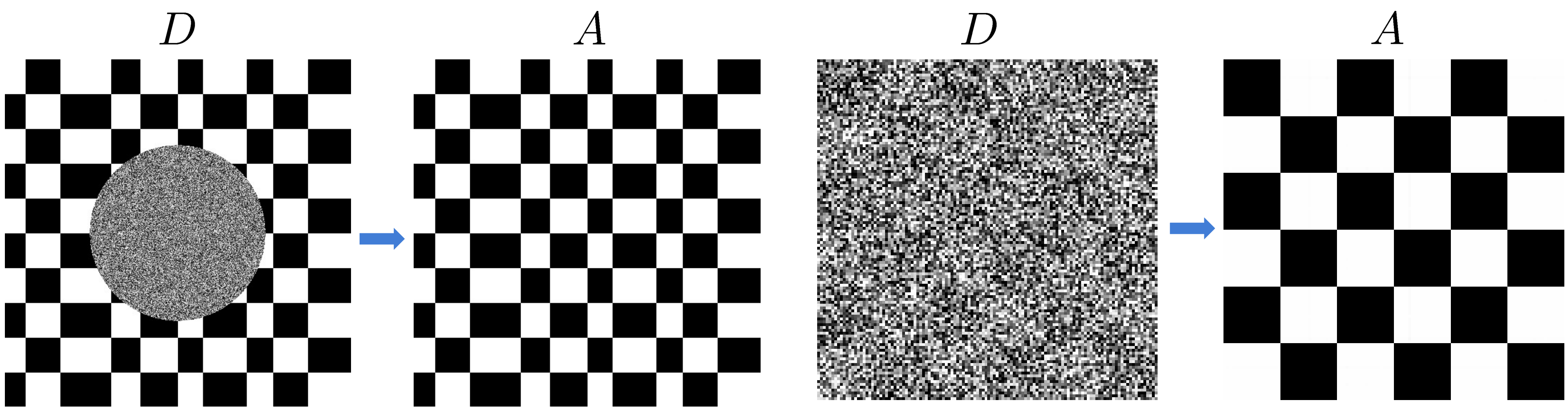


Sparse Structures



Repairing Images: Highly Robust Repairing of Low-rank Textures!





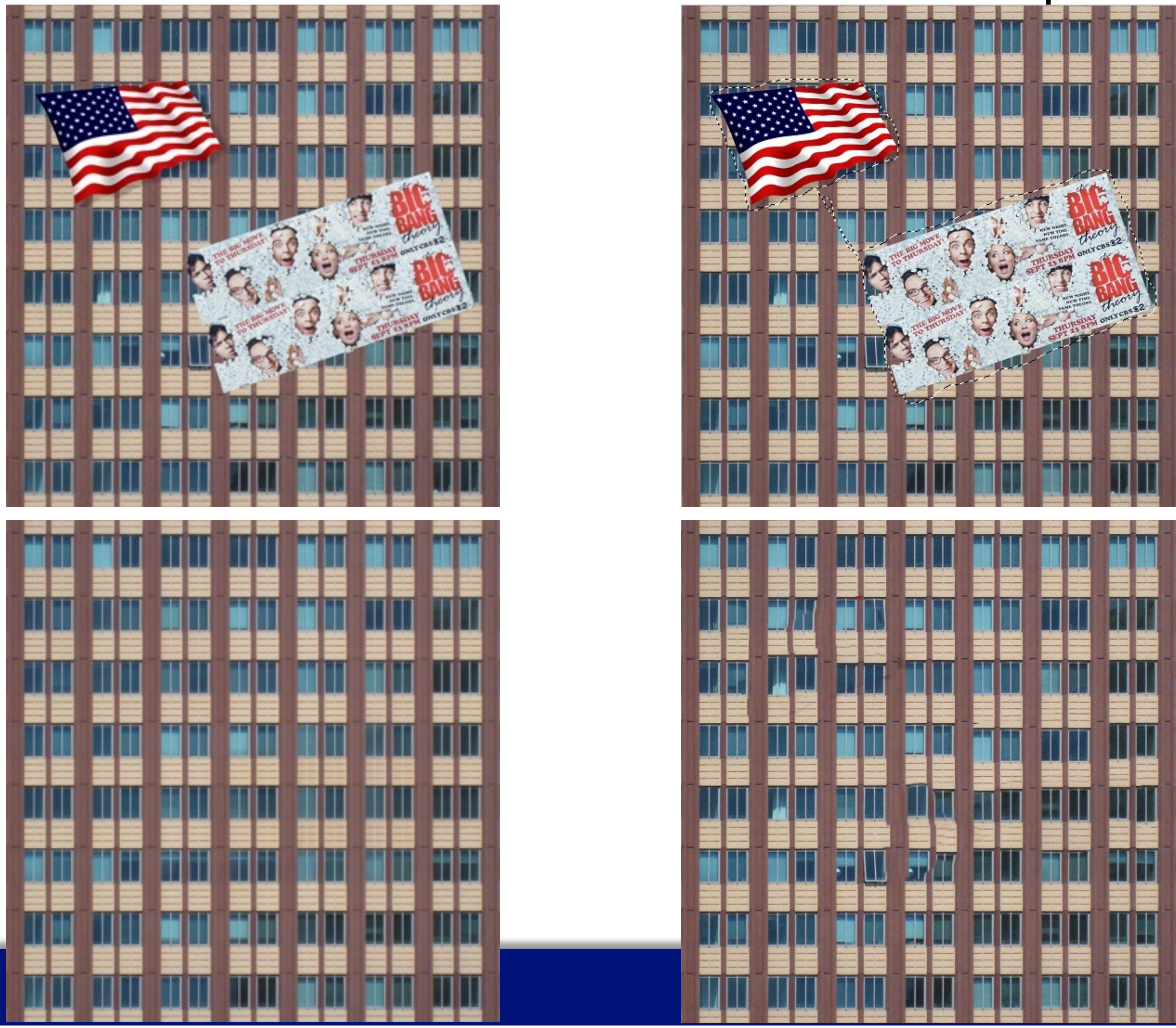
Liang, Ren, Zhang, and Ma, in ECCV 2012.

Repairing Low-rank Textures

Low-rank Method | Photoshop

Input

Output



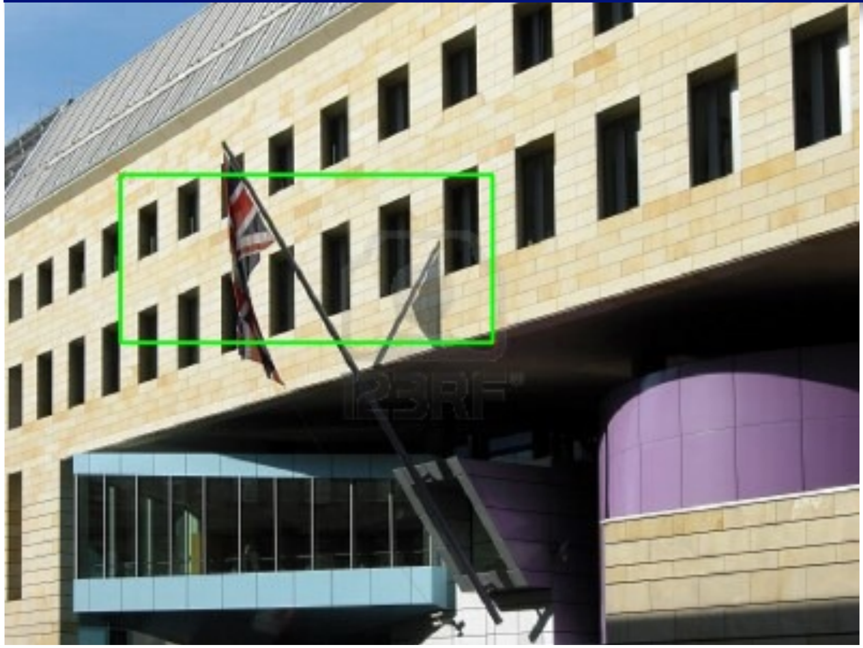
Repairing (Distorted) Low-rank Textures

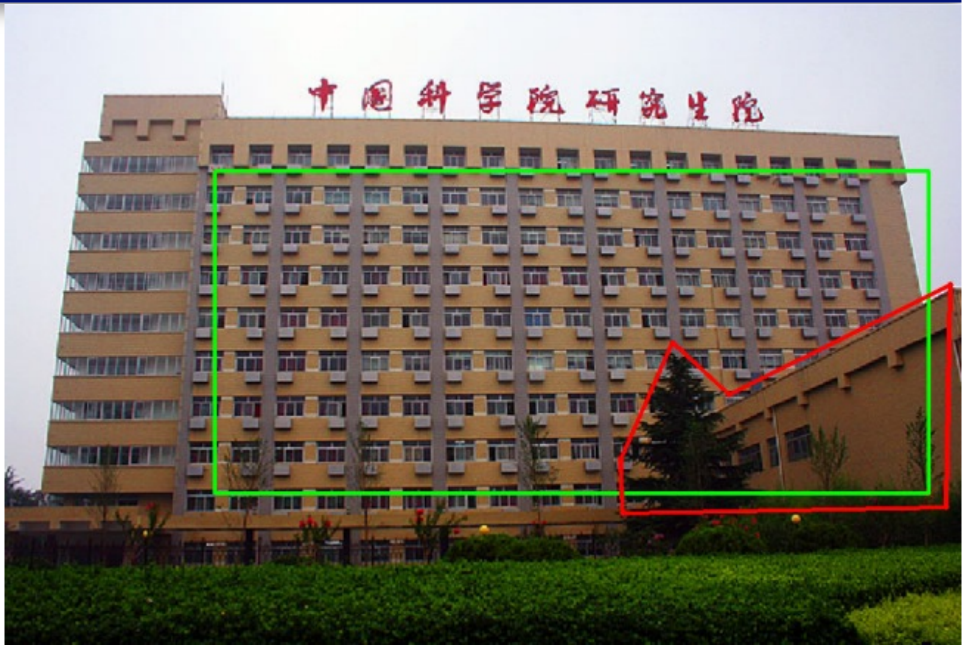
Low-rank Method | Photoshop

Input

Output

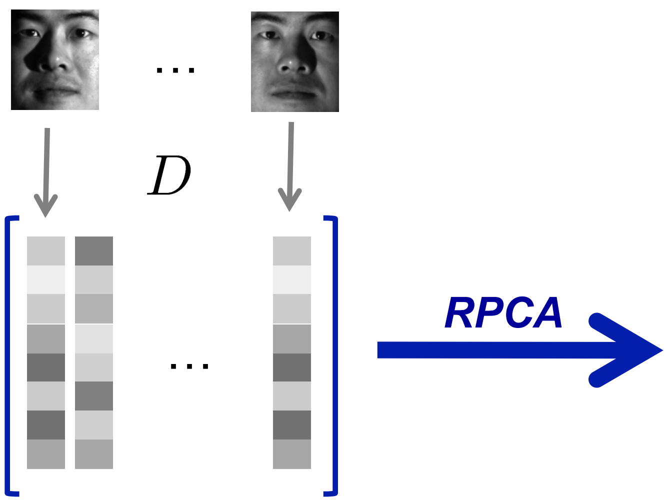
Structured Texture Completion and Repairing

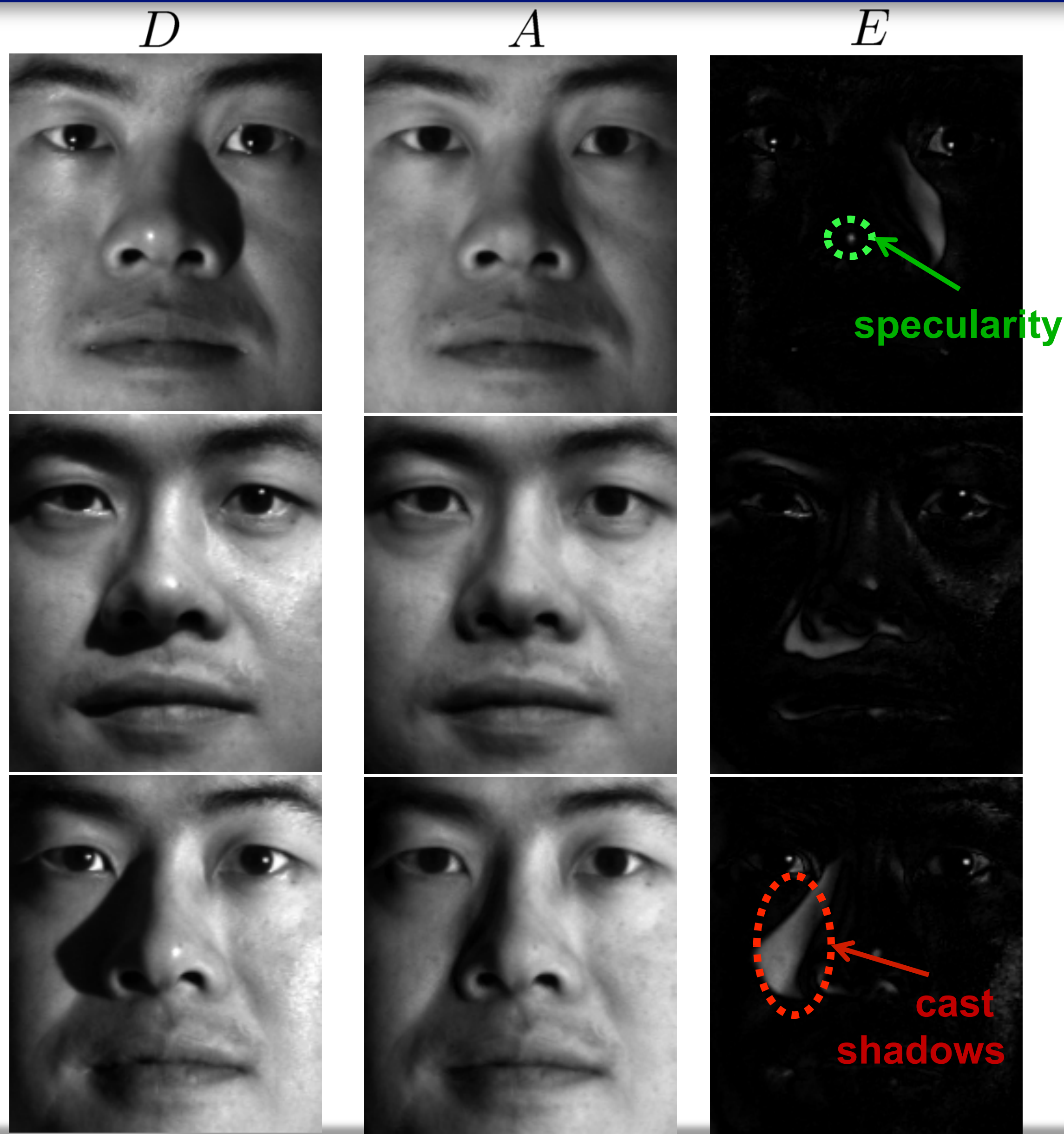




Repairing Multiple Correlated Images

58 images of one person
under varying lighting:

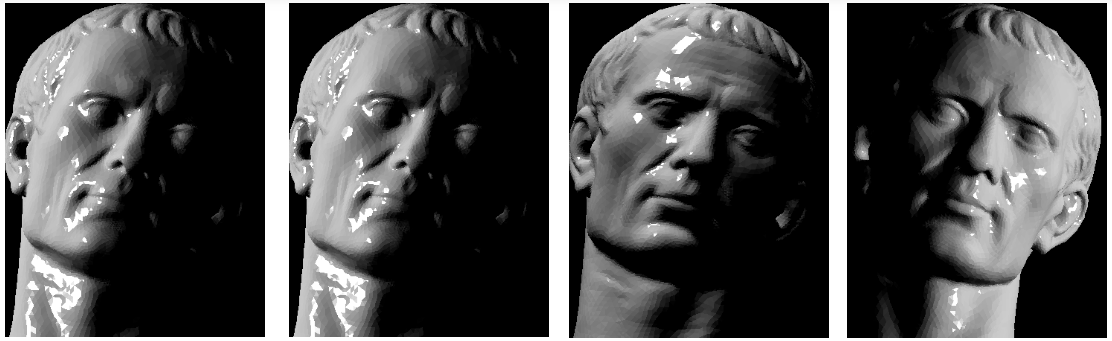




Candes, Li, Ma, and Wright, Journal of the ACM, May 2011.

Repairing Images: robust photometric stereo

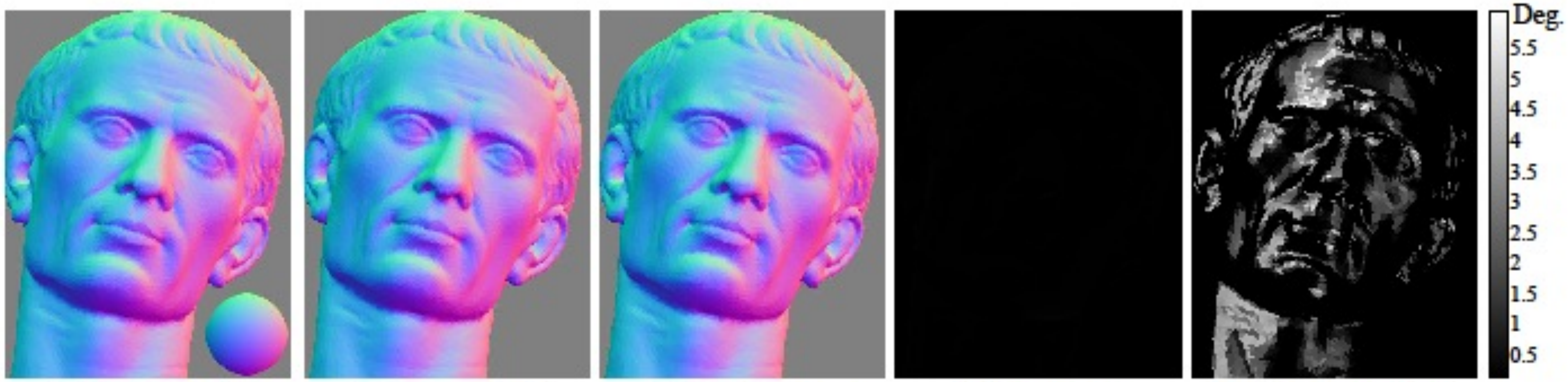
Input images



$$\min \ \|A\|_* + \lambda\|E\|_1 \quad \text{subj} \quad D = \mathcal{P}_\Omega(A + E).$$

$\Omega^c \sim \text{shadow}(20.7\%)$

$E \sim \text{specularities}(13.6\%)$



(a) Ground truth (b) Our method (c) Least Squares (d) Error map (our method) (e) Error map (LS)

	(d) Our method	(e) LS
Mean error	**0.014°**	0.96°
Max error	**0.20°**	8.0°

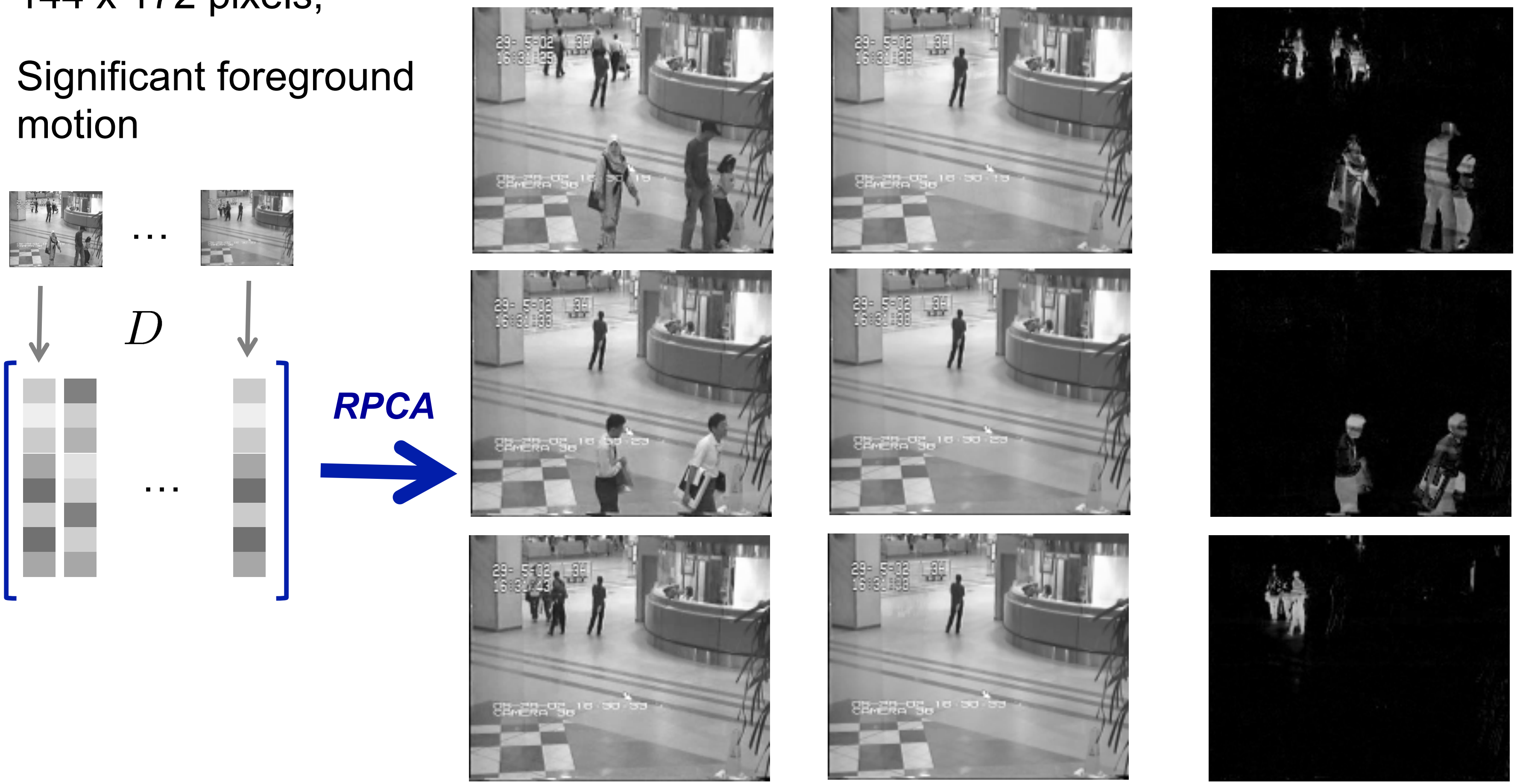
Repairing Video Frames: *background modeling from video*

Surveillance video

200 frames,
144 x 172 pixels,

Significant foreground motion

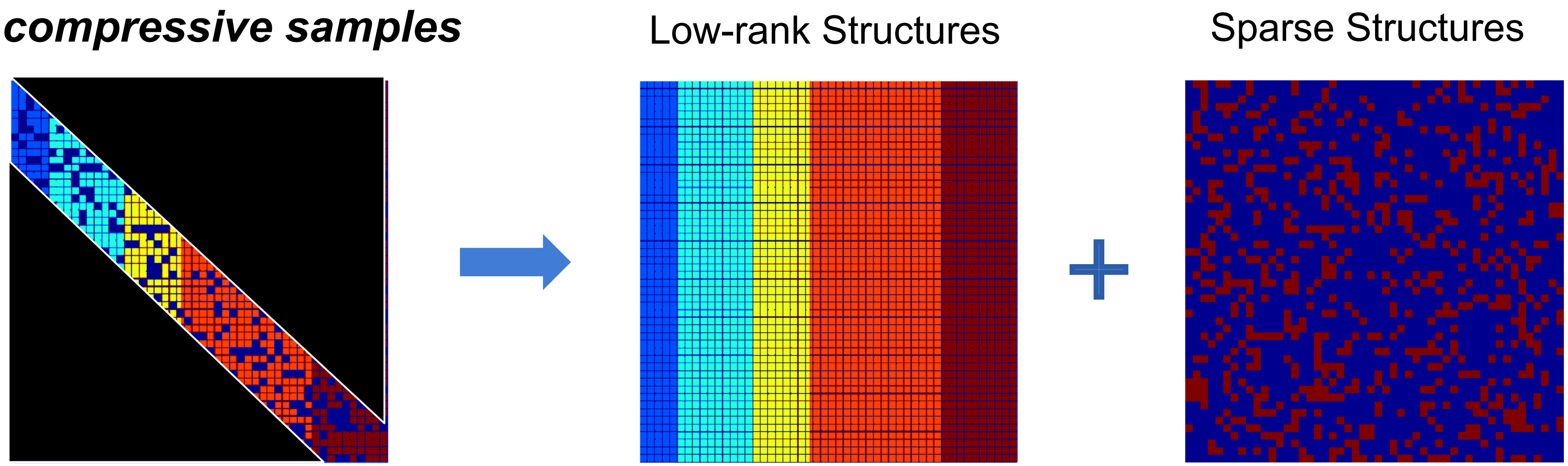
Video D = Low-rank appx. A + Sparse error E



Candès, Li, Ma, and Wright, JACM, May 2011.

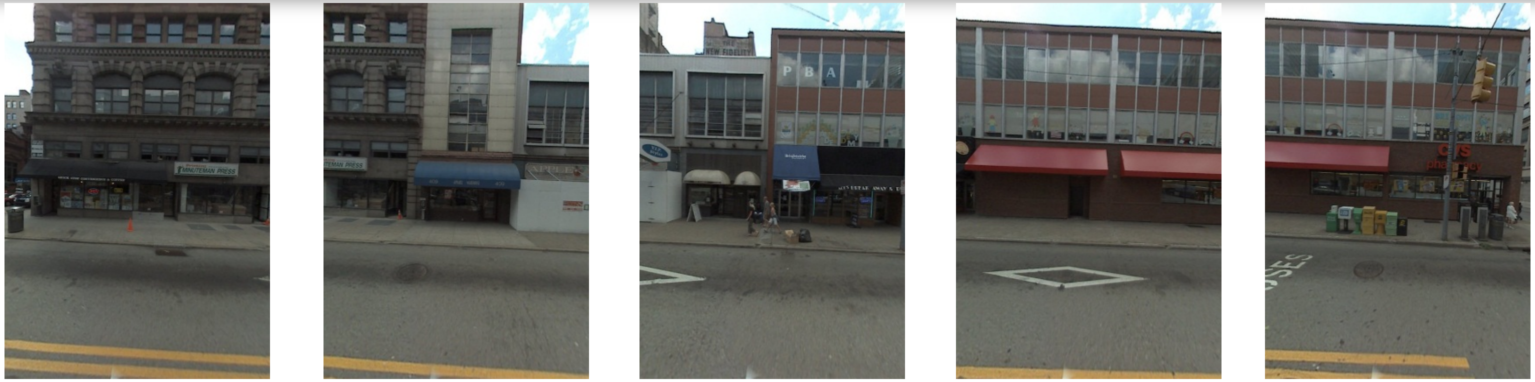
Implications: Highly Compressive Sensing of Structured Information!

Recover low-dimensional structures from diminishing fraction of corrupted measurements.



Repairing Video Frames: *Street Panorama*

D

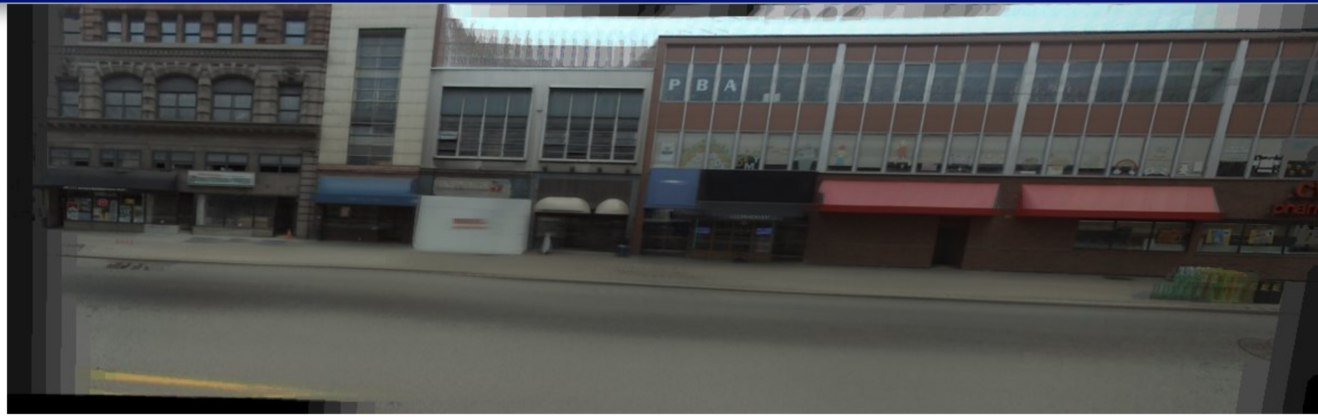


A

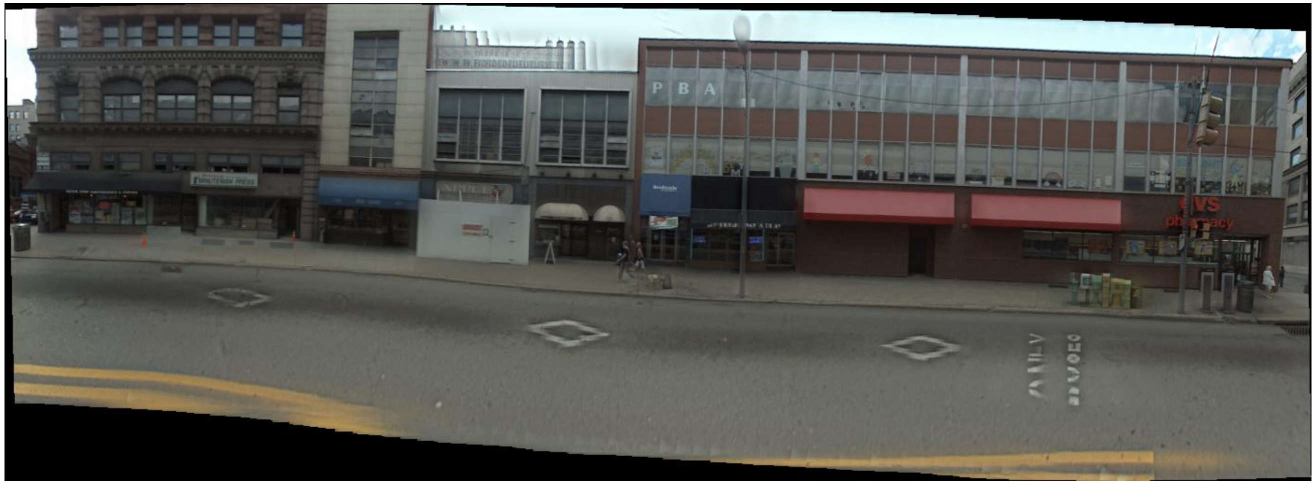
E

Repairing Video Frames: Street Panorama

Low-rank



AutoStitch



Photoshop

Repairing Video Frames: Street Panorama

Low-rank

AutoStitch

Photoshop

Street Panorama: Highly Compressive Sensing of Low-dim Structures!

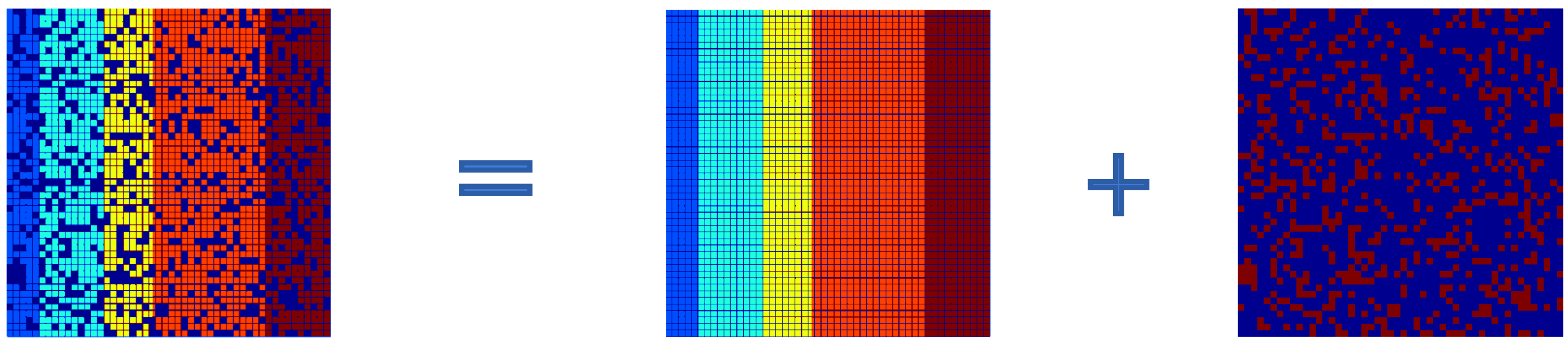
nips12_video.mp4

Sensing or Imaging of Low-rank and Sparse Structures

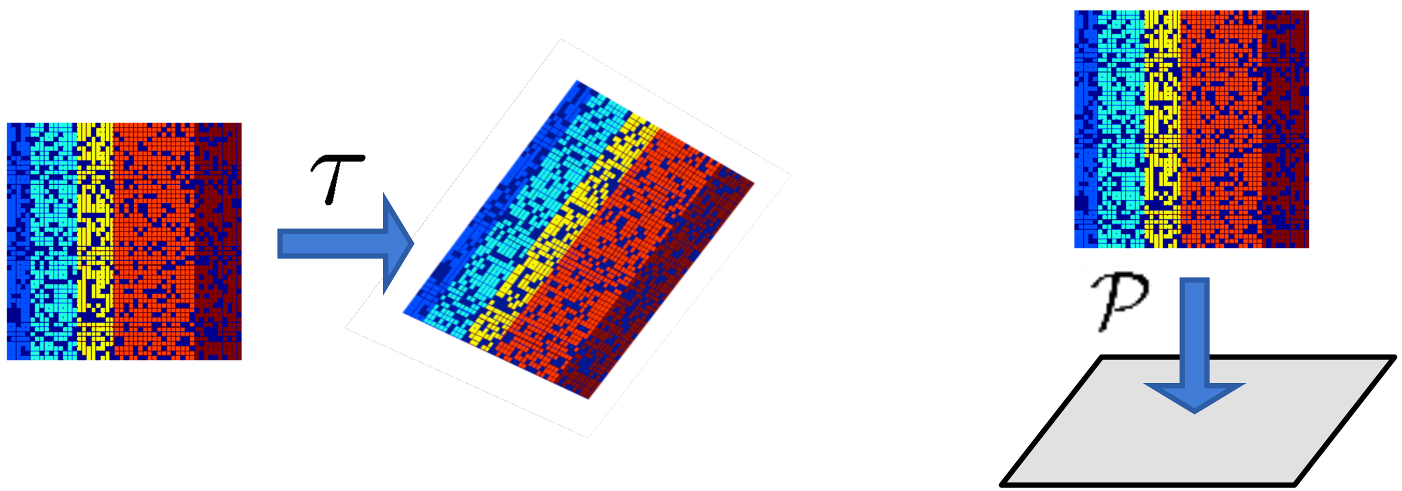
Fundamental Problem: ***How to recover low-rank and sparse structures from corrupted data***

Low-rank Structures

Sparse Structures

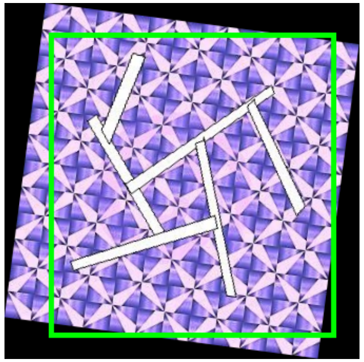


subject to either nonlinear deformation τ or linear compressive sampling $\mathcal{P}$?



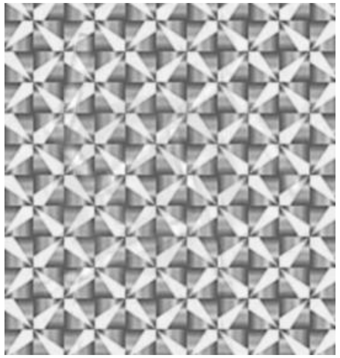
Reconstructing 3D Geometry and Structures

D – deformed observation



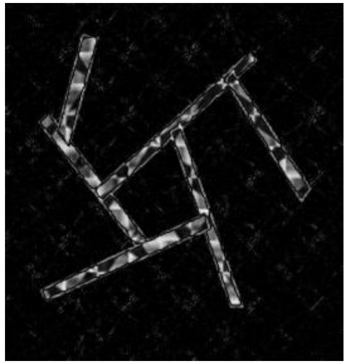
$\circ \, \tau \; =$

A – low-rank structures



$+$

E – sparse errors



Problem: Given $D \circ \tau = A_0 + E_0$, recover τ , A_0 and E_0 simultaneously.

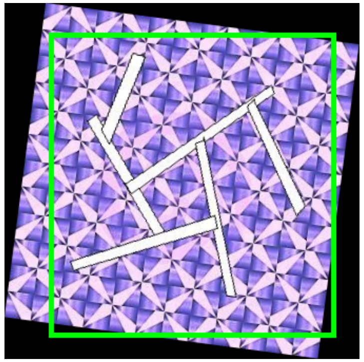
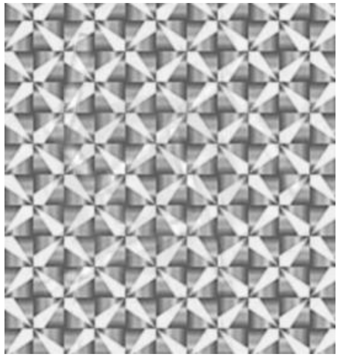
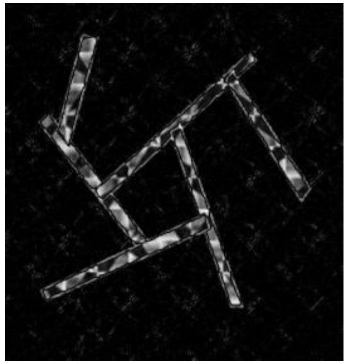
Low-rank component
(regular patterns…)

Sparse component
(occlusion, corruption, foreground…)

Parametric deformations
(affine, projective, radial distortion, 3D shape…)

Transform Invariant Low-rank Textures (TILT)

D – deformed observation $\quad$ A – low-rank structures $\quad$ E – sparse errors

 $\circ\, \tau \;=$  $+$ 

Objective: *Transformed Principal Component Pursuit:*

$$\min \ \|A\|_* + \lambda \|E\|_1 \quad \text{subj} \quad A + E = D \circ \tau$$

Solution: *Iteratively solving the linearized convex program:*

$$\min \ \|A\|_* + \lambda \|E\|_1 \quad \text{subj} \quad A + E = D \circ \tau_k + J \cdot \Delta\tau$$

Or reduced version: $\quad \text{subj} \quad \mathcal{P}_Q[A+E] = \mathcal{P}_Q[D \circ \tau_k], \ \mathcal{P}_Q[J] = 0$

THEORY – *Compressive Robust PCA*

Theorem 5 (Compressive Principal Component Pursuit). *Let* $A_0 \in \mathbb{R}^{m\times n}$, $m \geq n$ *have rank* $r \leq \rho_r \frac{m}{\mu^2 \log^2(n)}$, *and* E_0 *have a Bernoulli support with error probability* $\rho < \rho^\star$. *Let* $Q^\perp$ *be a random subspac of* $\mathbb{R}^{m\times n}$ *of dimension*

$$\dim(Q) \geq C_Q(\rho mn + mr) \cdot \log^2 m,$$

distributed according to the Haar measure, independent of the support of E_0. *Then with very high probability*

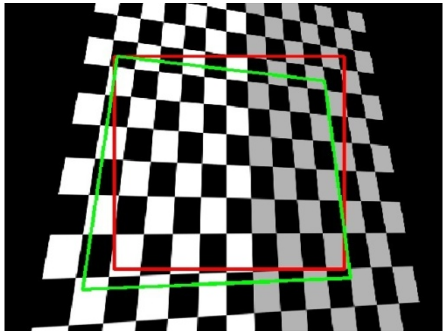
$$(A_0, E_0) = \arg\min \|A\|_* + \frac{1}{\sqrt{m}}\|E\|_1 \quad \text{subj} \quad \mathcal{P}_Q[A+E] = \mathcal{P}_Q[A_0+E_0],$$

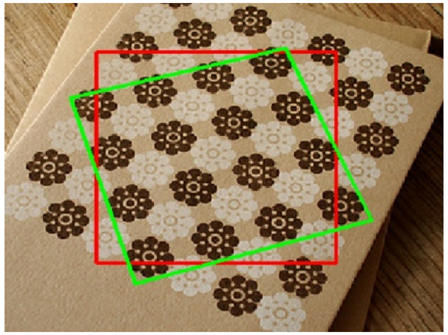
for some numerical constant ρ_r, C_p *and* $\rho^\star$, *and the minimizer is unique.*

A nearly optimal lower bound on minimum # of measurements!

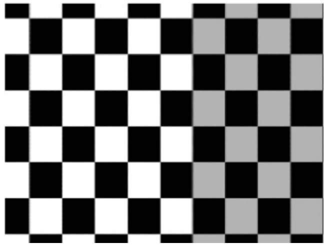
TILT: *Shape from texture*

Input (red window D)



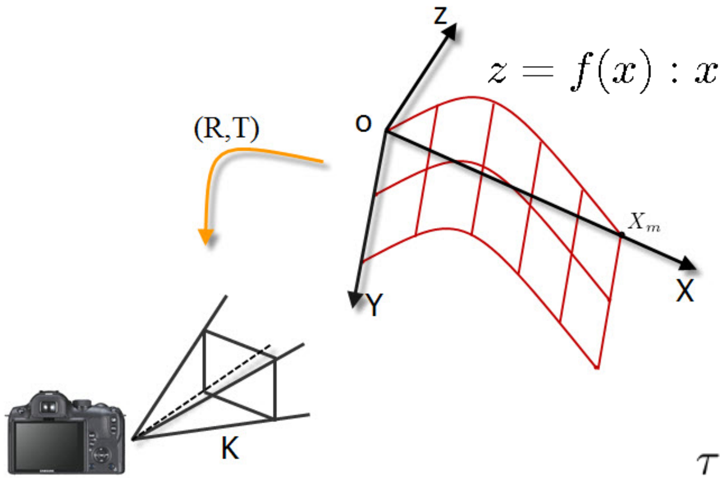


Output (rectified green window A)



Zhang, Liang, Ganesh, Ma, ACCV’10, IJCV’12

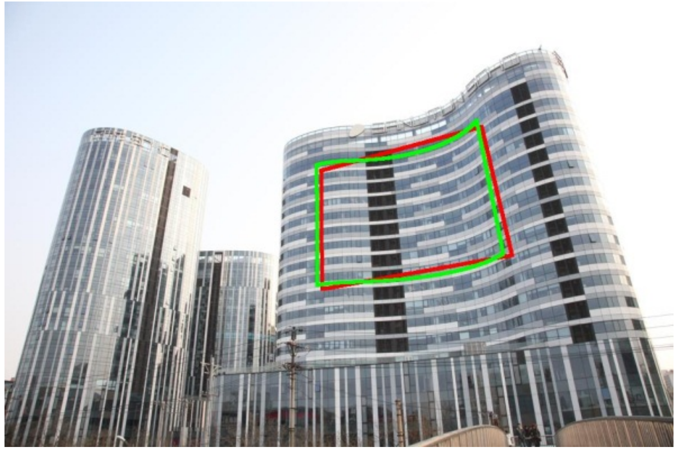
TILT: *Shape and geometry from textures*



$$z = f(x) : x(x - x_m)\sum_{i=1}^{d} a_i x^i$$

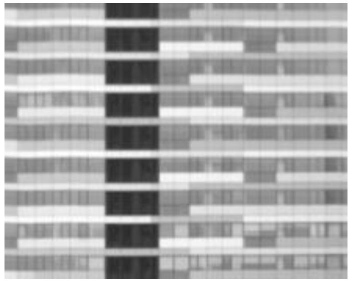
$$D \circ \tau = A + E$$

$$\tau = (K, R, T, \{a_i\})$$

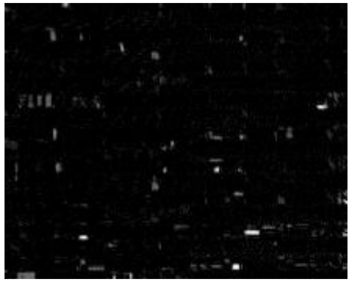


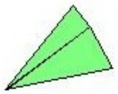
D

A

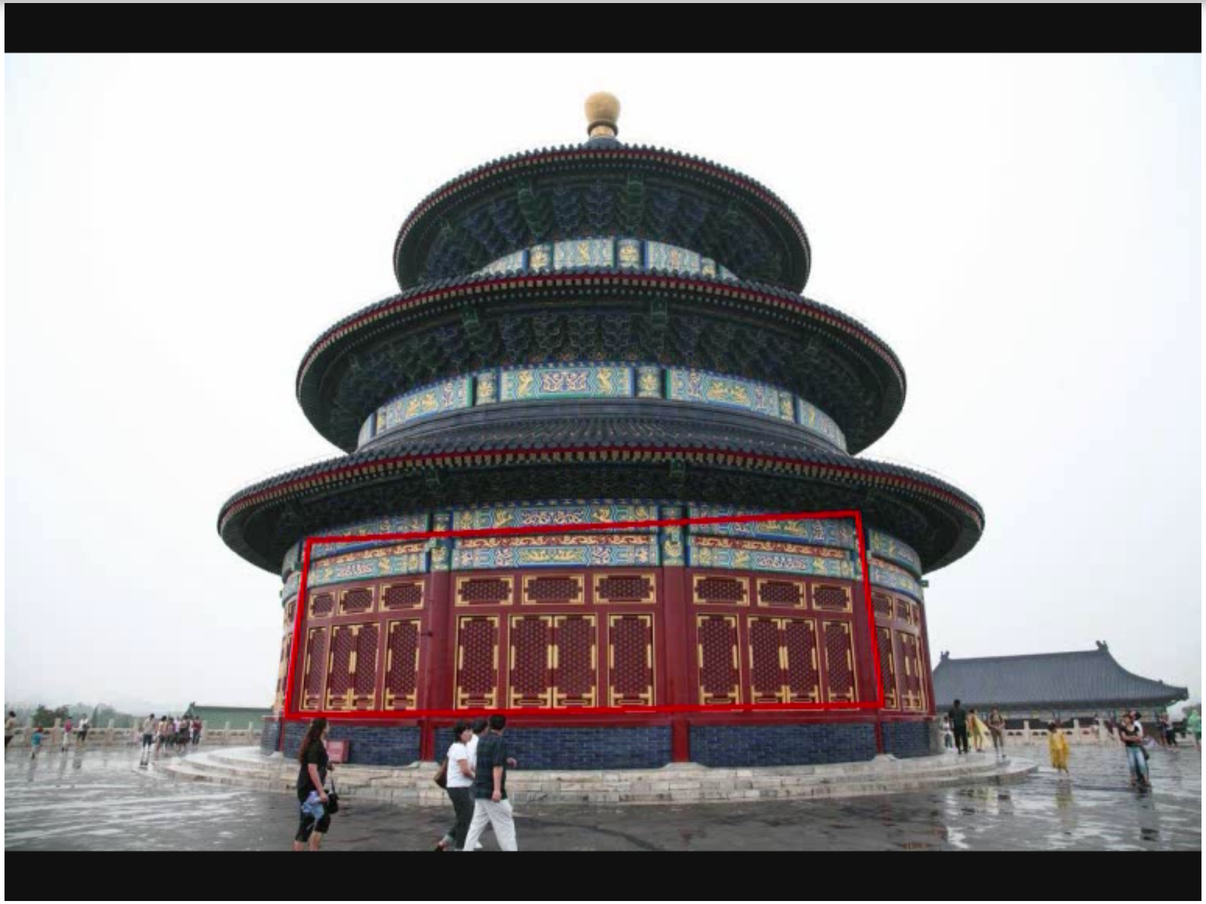


E



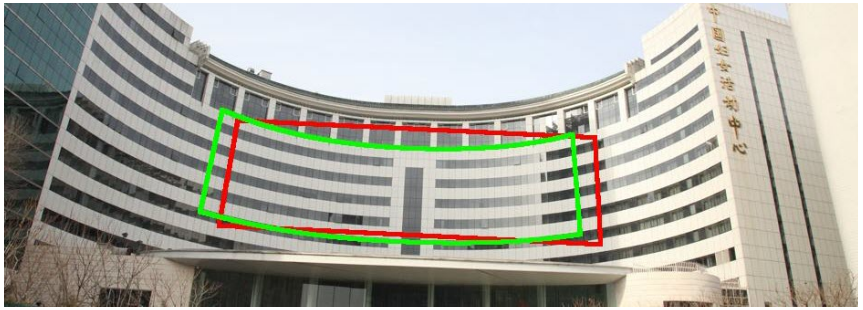


TILT: *Shape and geometry from textures*

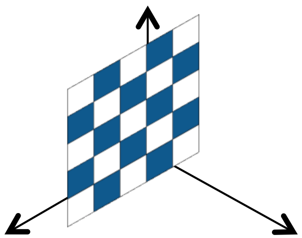


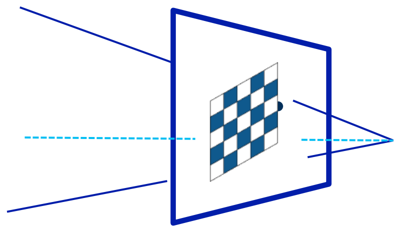
360^o panorama

TILT: *Virtual reality*



TILT: *Camera Calibration with Radial Distortion*

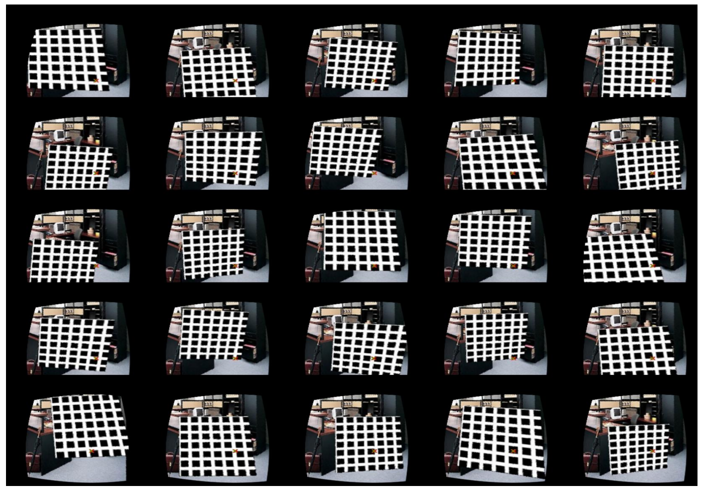




$$r = \sqrt{x_0^2 + y_0^2}, f(r) = 1 + kc(1)r^2 + kc(2)r^4 + kc(5)r^6$$

$$\begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} f(r)x_0 + 2kc(3)x_0y_0 + kc(4)(r^2 + 2x_0^2) \\ f(r)y_0 + 2kc(4)x_0y_0 + kc(3)(r^2 + 2y_0^2) \end{pmatrix}$$

$$K = \begin{bmatrix} f_x & \theta & o_x \\ 0 & f_y & o_y \\ 0 & 0 & 1 \end{bmatrix}$$



TILT: *Camera Calibration with Radial Distortion*

$$\min \sum_{i=1}^{N} \|A_i\|_* + \lambda \|E_i\|_1 \quad \text{subj} \quad A_i + E_i = D \circ (\tau_0, \tau_i)$$

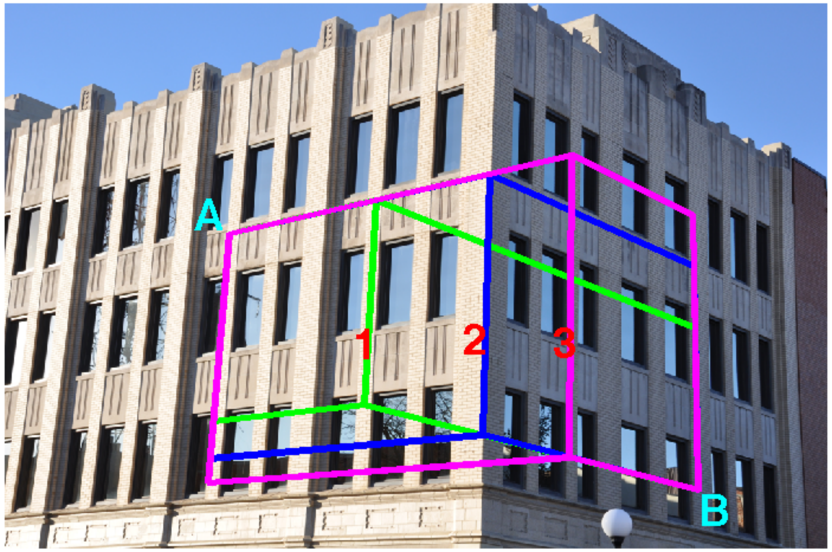
$$\tau_0 = (K, K_c), \quad \tau_i = (R_i, T_i).$$

Previous approach

Low-rank method

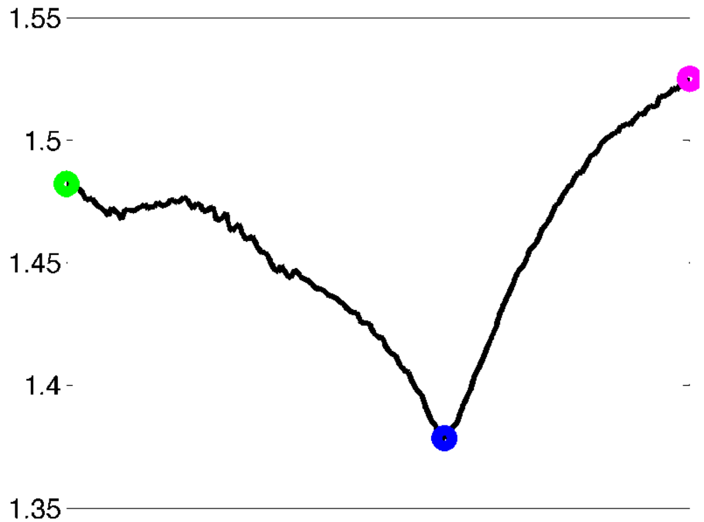
Zhang, Matsushita, and Ma, in CVPR 2011

TILT: *Holistic 3D Reconstruction of Urban Scenes*



$$\min \|{\color{red}A}\|_* + \|{\color{green}E}\|_1 \quad \text{s.t.}$$

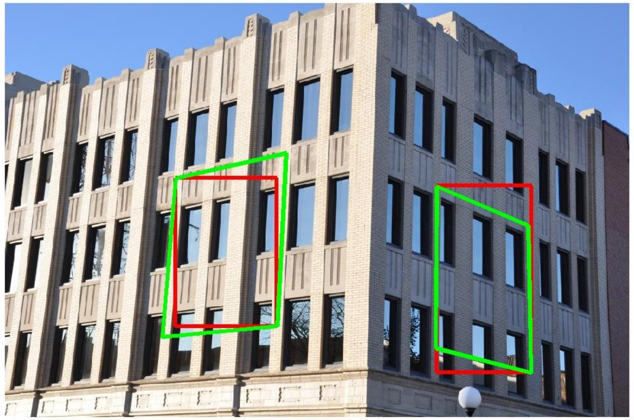
$${\color{red}A} + {\color{green}E} = [D_1 \circ \tau_1, D_2 \circ \tau_2]$$

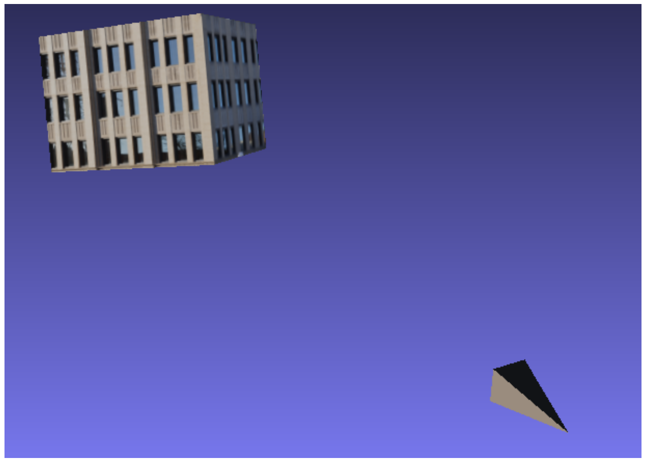


Mobahi, Zhou, and Ma, in ICCV 2011

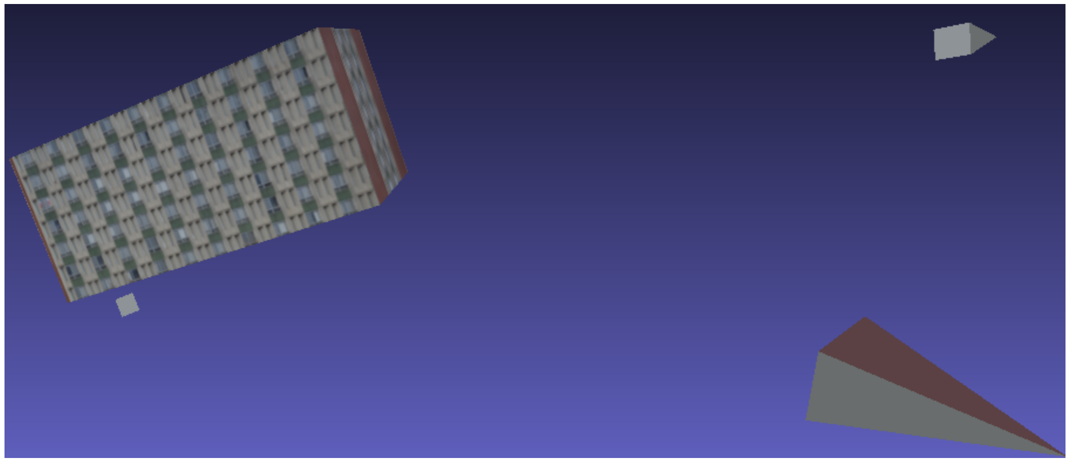
TILT: *Holistic 3D Reconstruction of Urban Scenes*

From one input image





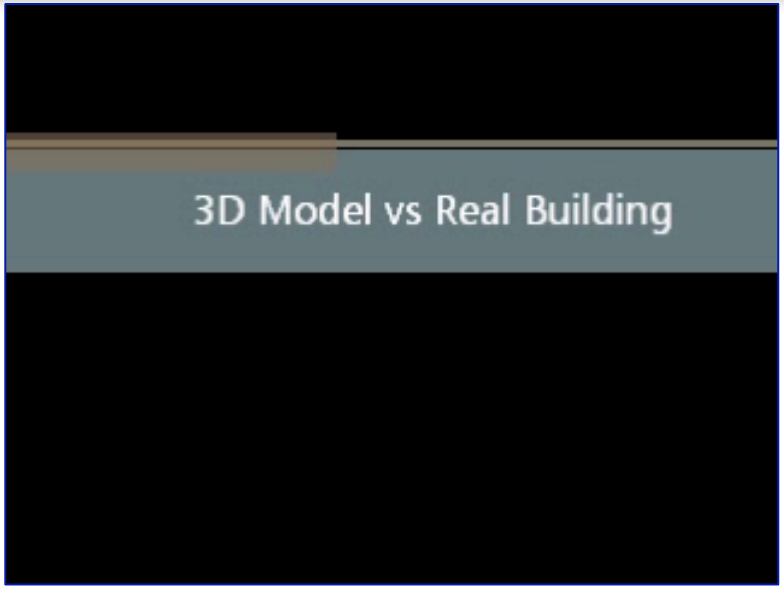
From four input images

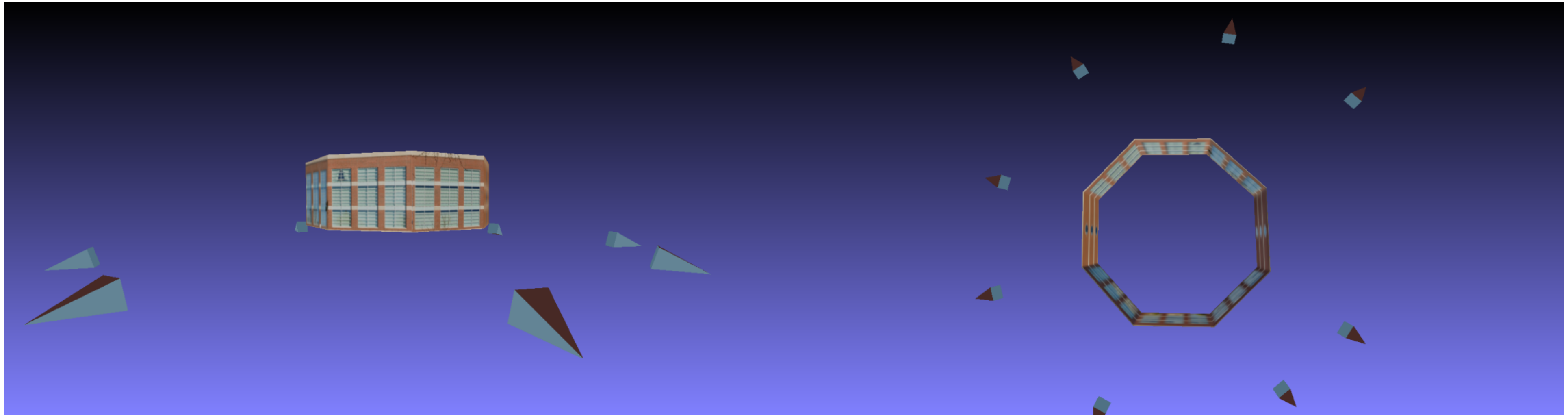


Mobahi, Zhou, and Ma, in ICCV 2011

TILT: *Holistic 3D Reconstruction of Urban Scenes*

From eight input images





Mobahi, Zhou, and Ma, in ICCV 2011

Virtual reality in urban scenes

Registering Multiple Images: Robust Alignment

D – corrupted & misaligned observation

A – aligned low-rank signals

E – sparse errors

Problem: Given $D \circ \tau = A_0 + E_0$, recover τ , A_0 and E_0 .

Parametric deformations (rigid, affine, projective…)

Low-rank component

Sparse component

Solution: Robust Alignment via Low-rank and Sparse (**RASL**) Decomposition

Iteratively solving the linearized convex program:

$$\min \ \|A\|_* + \lambda\|E\|_1 \quad \text{subj} \quad A + E = D \circ \tau_k + J\Delta\tau$$

$$\left(\text{or} \quad Q(A+E) = QD \circ \tau_k, \ QJ = 0\right)$$

RASL: *Aligning Face Images from the Internet*

*48 images collected from internet

Peng, Ganesh, Wright, Ma, CVPR'10, TPAMI'11

RASL: *Faces Detected*

Input: faces detected by a face detector (D)

Average

RASL: *Faces Aligned*

Output: aligned faces ($D \circ \tau$)

Average

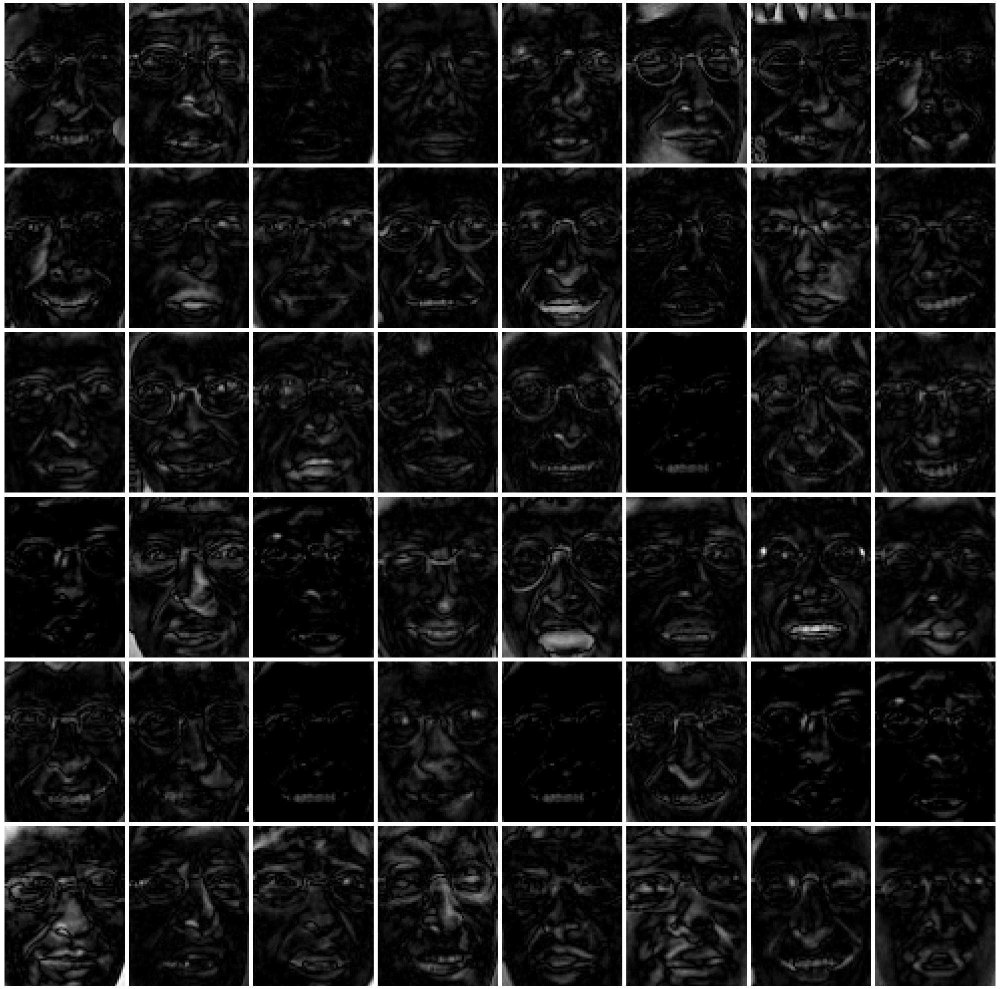
RASL: *Faces Repaired and Cleaned*

Output: clean low-rank faces (A)

Average

RASL: *Sparse Errors of the Face Images*

Output: sparse error images (E)



RASL: *Video Stabilization and Enhancement*

Original video (D)

Aligned video ($D \circ \tau$)

Low-rank part (A)

Sparse part (E)

RASL: *Aligning Handwritten Digits*

D

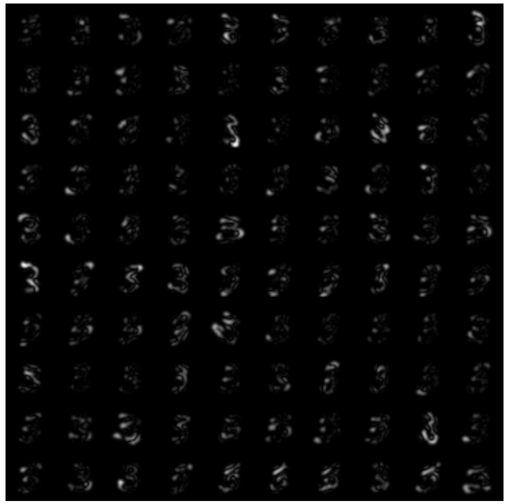
Learned-Miller PAMI'06

Vedaldi CVPR'08

$D \circ \tau$

A

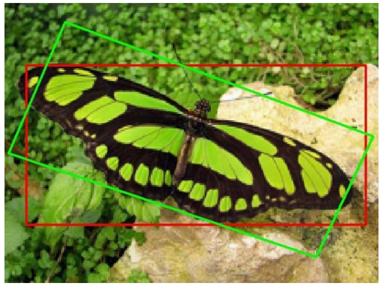
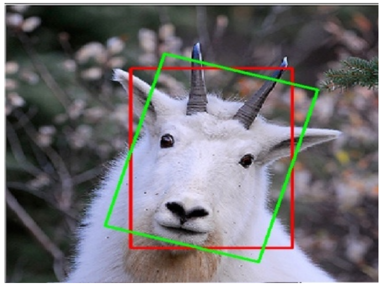
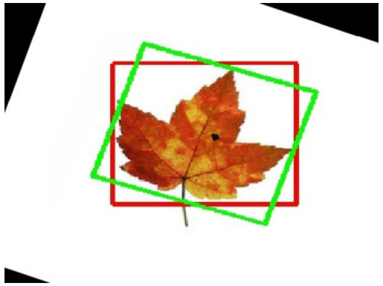
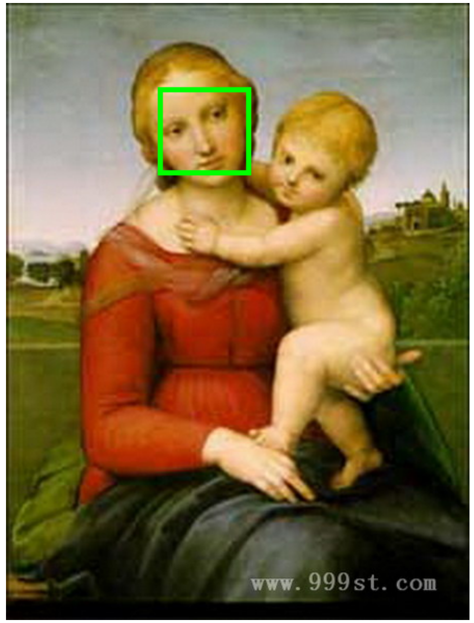
E



Peng, Ganesh, Wright, Ma, CVPR'10, TPAMI'11

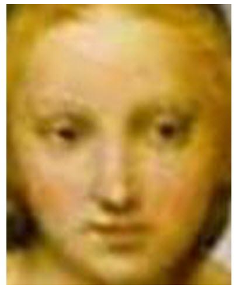
Object Recognition: *Rectifying Pose of Objects*

Input (red window D)

Output (rectified green window A)



Zhang, Liang, Ganesh, Ma, ACCV'10 and IJCV'12

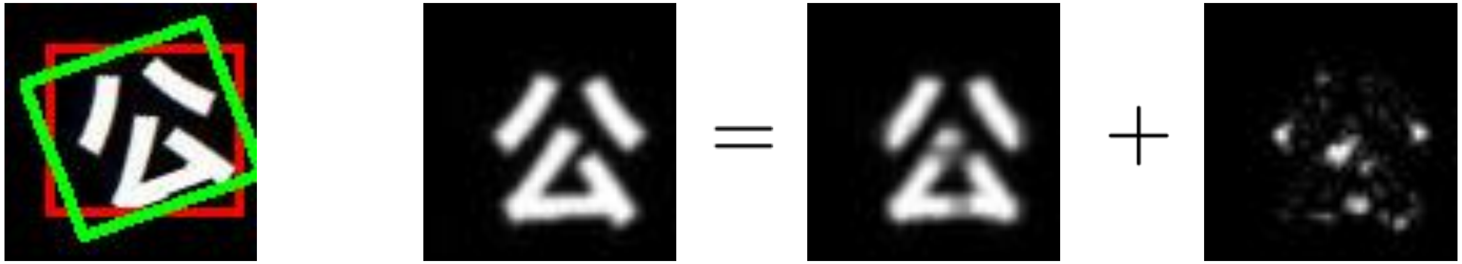
Object Recognition: *Regularity of Texts at All Scales!*

Input (red window D)

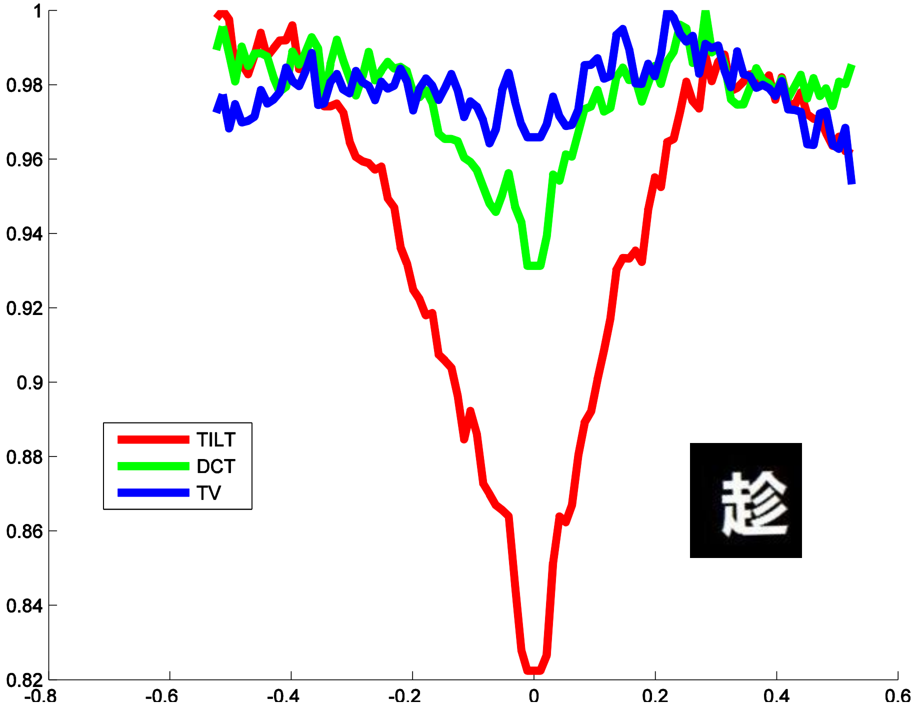
Output (rectified green window A)

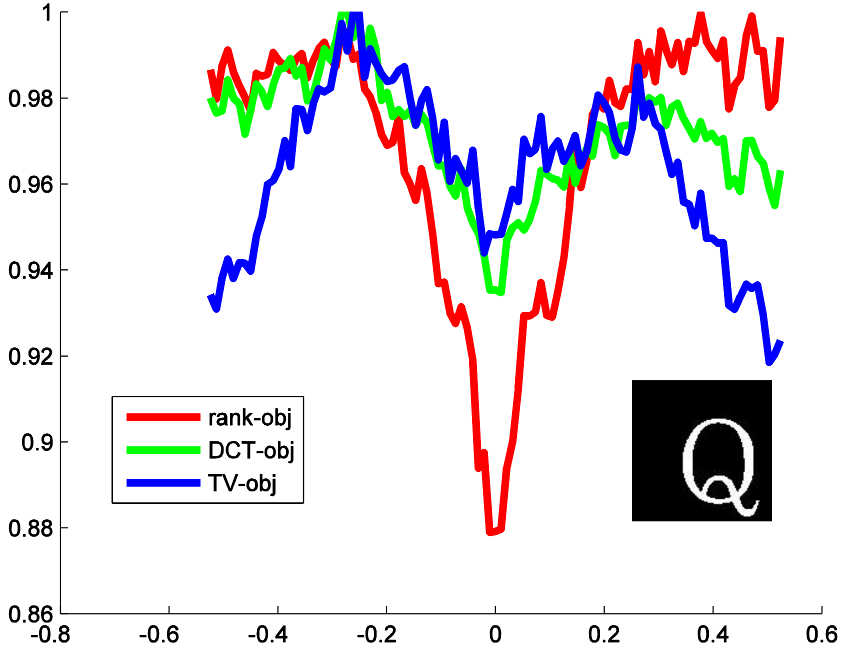
Zhang, Liang, Ganesh, Ma, ACCV'10 and IJCV'12

Recognition: *Character/Text Rectification*



$$D \qquad D \circ \tau = A + E$$

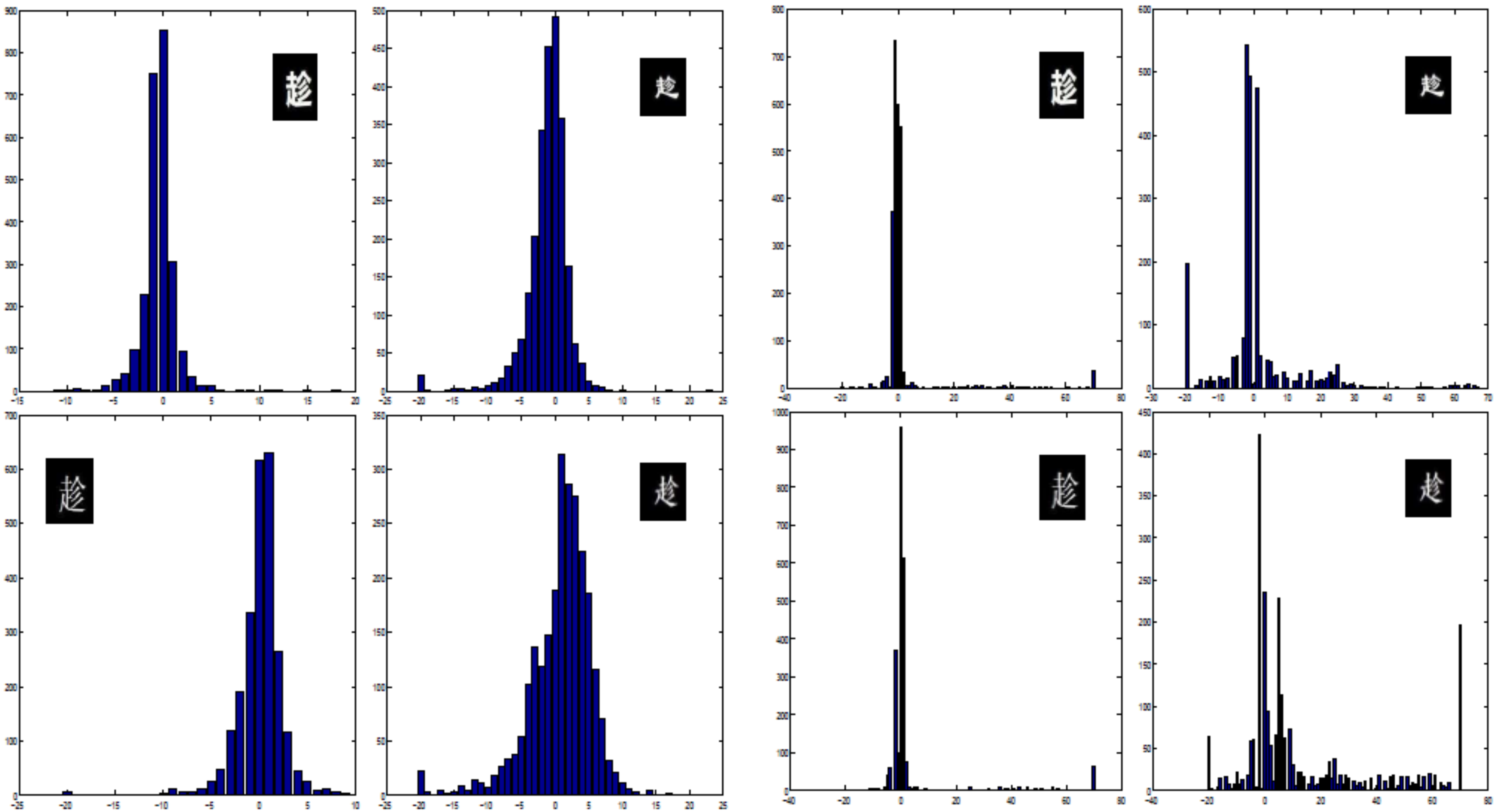




Xin Zhang, Zhouchen Lin, and Ma, ICDAR 2013

Recognition: *Character/Text Rectification*

TILT versus Hough Transform



Recognition: Street Sign Rectification

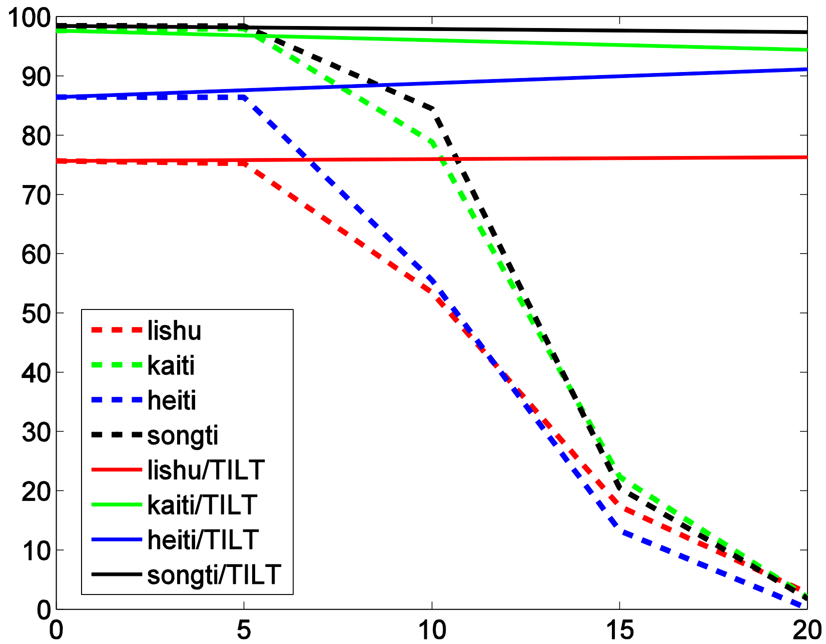
A_1 A_2 A_3 A_4

$$\min \sum_{i=1}^{4} \|A_i\|_* + \lambda \|E_i\|_1$$

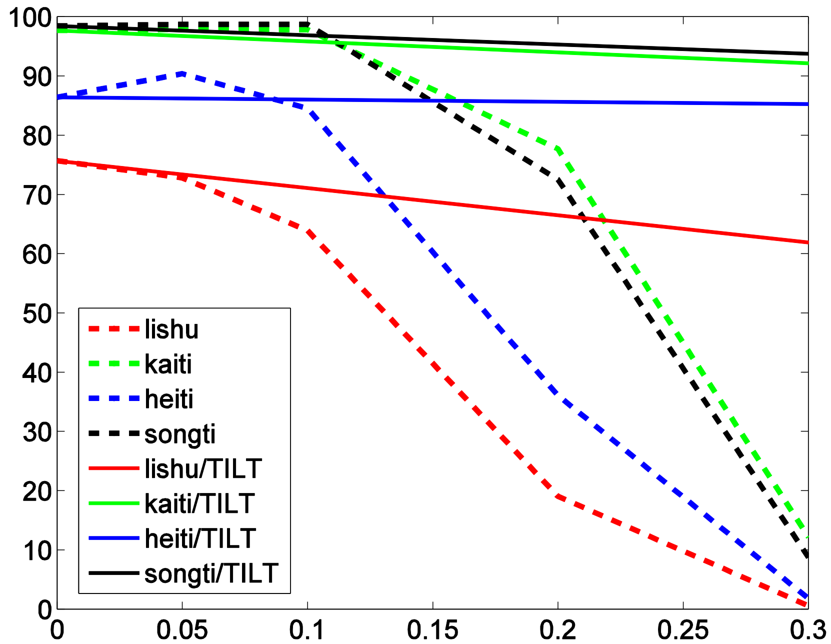
$$\text{subj} \quad D \circ \tau = [A_1 \cdots A_4] + [E_1 \cdots E_4].$$

Recognition: Character Rectification and Recognition

Microsoft OCR for rotated characters
(2,500 common Chinese characters)



Microsoft OCR for skewed characters
(2,500 common Chinese characters)



Take-home Messages for Visual Data Processing:

1. (Transformed) **low-rank and sparse** structures are central to visual data modeling, processing, and analyzing;

2. Such structures can now be extracted **correctly, robustly, and efficiently**, from raw image pixels (or high-dim features);

3. These new algorithms **unleash tremendous local or global information** from single or multiple images, emulating or surpassing human capability;

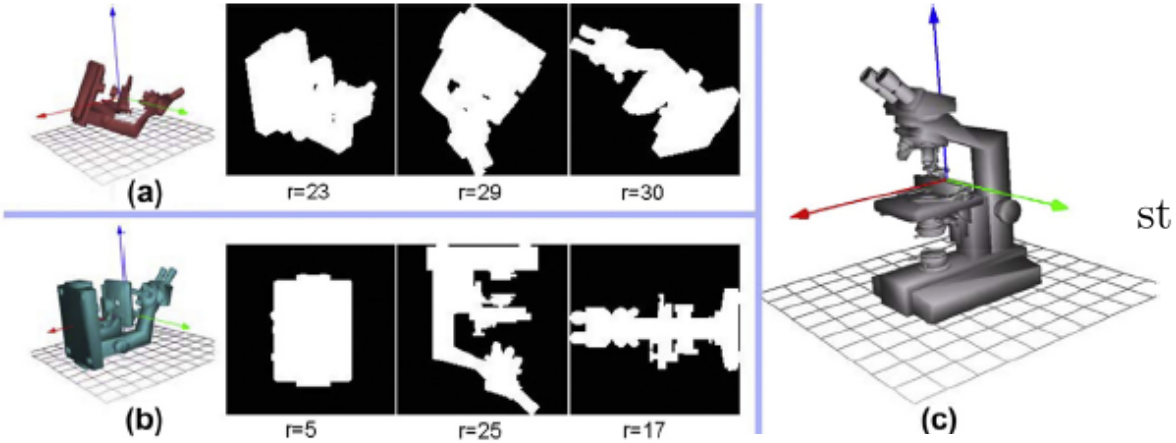
4. These algorithms start to exert significant impact on **image/video processing, 3D reconstruction, and object recognition**.

… …

But try not to abuse or misuse them…

Other Applications: *Upright orientation of man-made objects*

TILT for 3D: Unsupervised upright orientation of man-made 3D objects



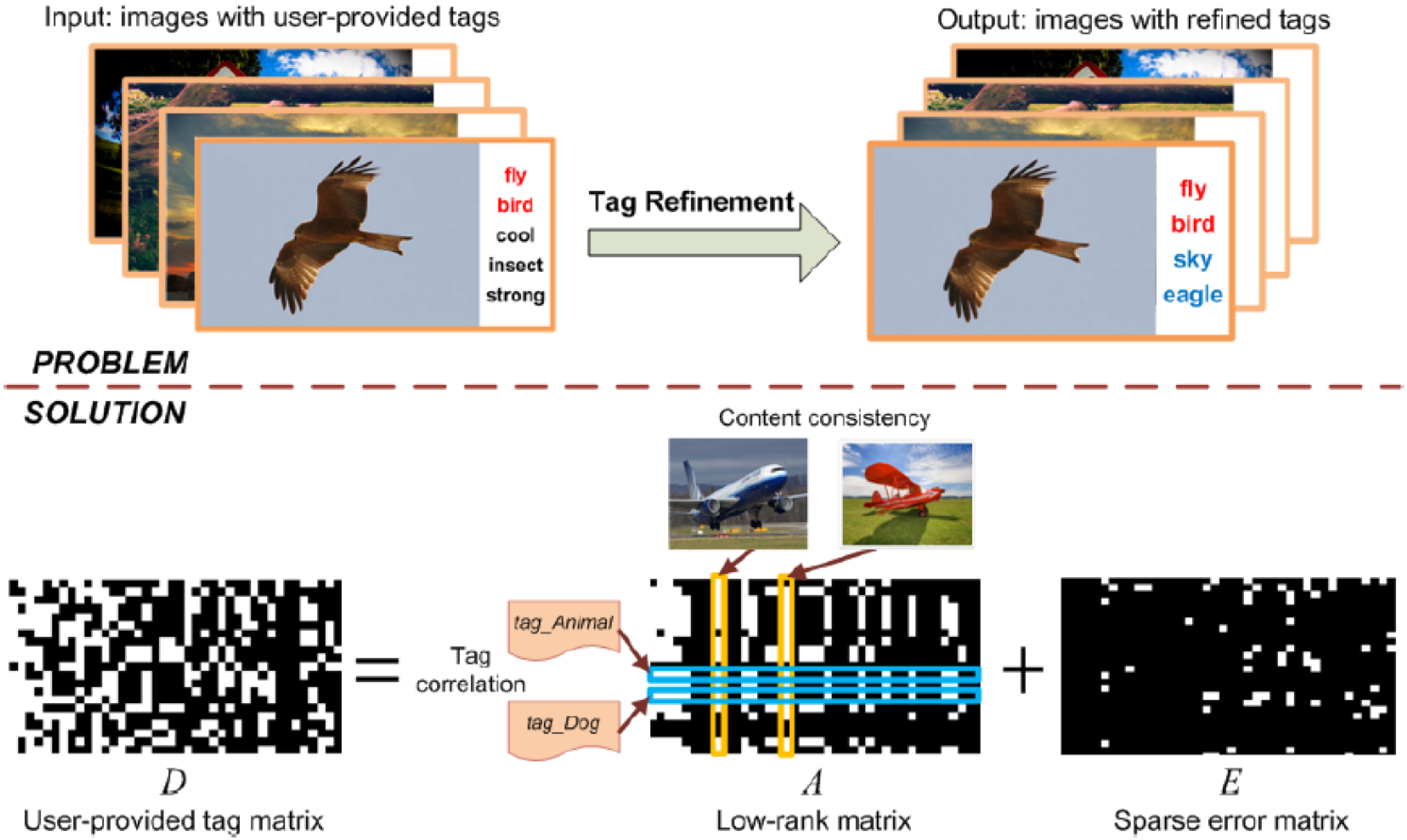
$$\min \sum_{i=1}^{3} \|A_i\|_* + \lambda \|E_i\|_1$$

$$\text{st } D \circ \tau = [A_1, A_2, A_3] + [E_1, E_2, E_3].$$

Fig. 10. More models which have been successfully tested through our algorithm.

Jin, Wu, and Liu of USTC, China, *Graphical Models*, 2012.

Other Data/Applications: Web Image/Tag Refinement



Zhu, Yan of NUS, Singapore, ACM MM 2010.

Other Data/Applications: Web Document Corpus Analysis

Latent Semantic Indexing: the classical solution (PCA)

Documents

Words

CHRYSLER SETS STOCK SPLIT, HIGHER DIVIDEND

Chrysler Corp said its board declared a three-for-two stock split in the form of a 50 pct stock dividend and raised the quarterly dividend by seven pct.

The company said the dividend was raised to 37.5 cts a share from 35 cts on a pre-split basis, equal to a 25 ct dividend on a post-split basis.

Chrysler said the stock dividend is payable April 13 to holders of record March 23 while the cash dividend is payable April 15 to holders of record March 23. It said cash will be paid in lieu of fractional shares.

With the split, Chrysler said 13.2 mln shares remain to be purchased in its stock repurchase program that began in late 1984. That program now has a target of 56.3 mln shares with the latest stock split.

Chrysler said in a statement the actions "reflect not only our outstanding performance over the past few years but also our optimism about the company's future."

D

d_{ij} word frequency (or TF/IDF)

$$D = A + Z$$
$$= U_1 \Sigma_1 V_1^T + \underline{U_2 \Sigma_2 V_2^T}$$

Dense, difficult to interpret

a better model/solution?

$$D = A + \underline{E}$$

Low-rank "background" topic model

Informative, discriminative "keywords"

Other Data/Applications: Sparse Keywords Extracted

Reuters-21578 dataset: 1,000 longest documents; 3,000 most frequent words

CHRYSLER SETS STOCK SPLIT, HIGHER DIVIDEND

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Other Data/Applications: Protein-Gene Correlation

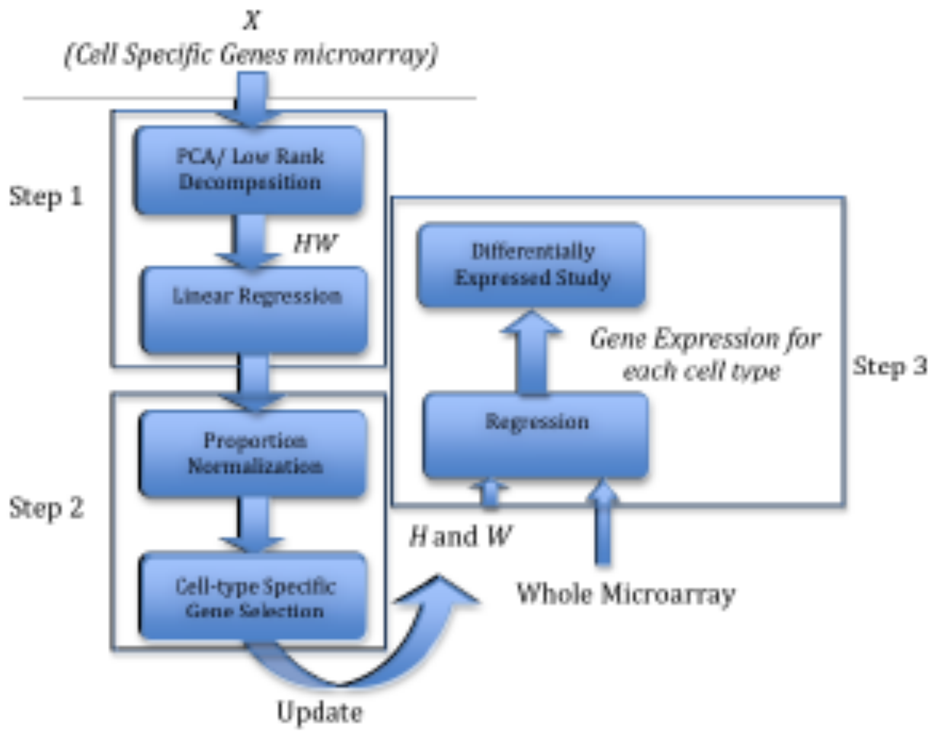


Fig. 1. The diagram of the workflow of the method presented in this paper.

Microarray data

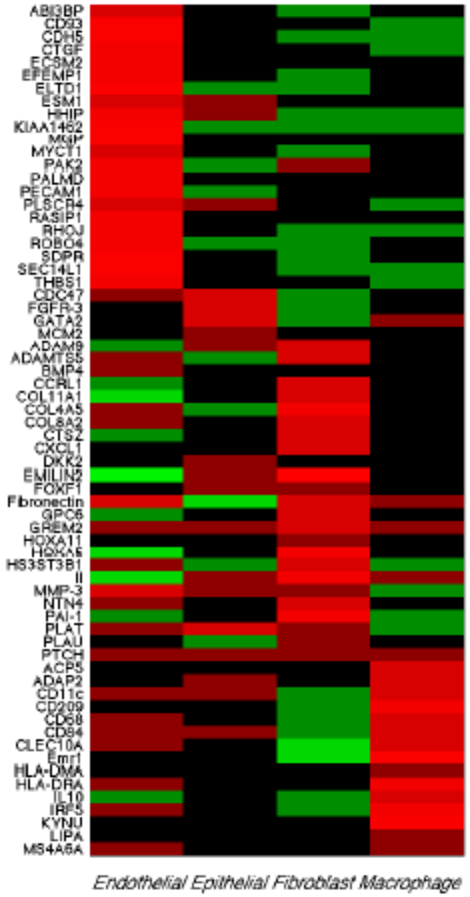


Fig. 6. HeatMap of estimated gene signatures for the sorted cell specific genes after adjustments based on fold changes. RPCA is used in the first step. It is clear that this matrix is close to a block diagonal structure.

Wang, Machiraju, and Huang of Ohio State Univ. , Bioinformatics.

Other Data: Time Series Gene Expressions

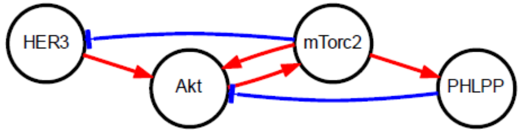


Figure S3. Abstract HER2 overexpressed breast cancer model by Dr. Moasser.

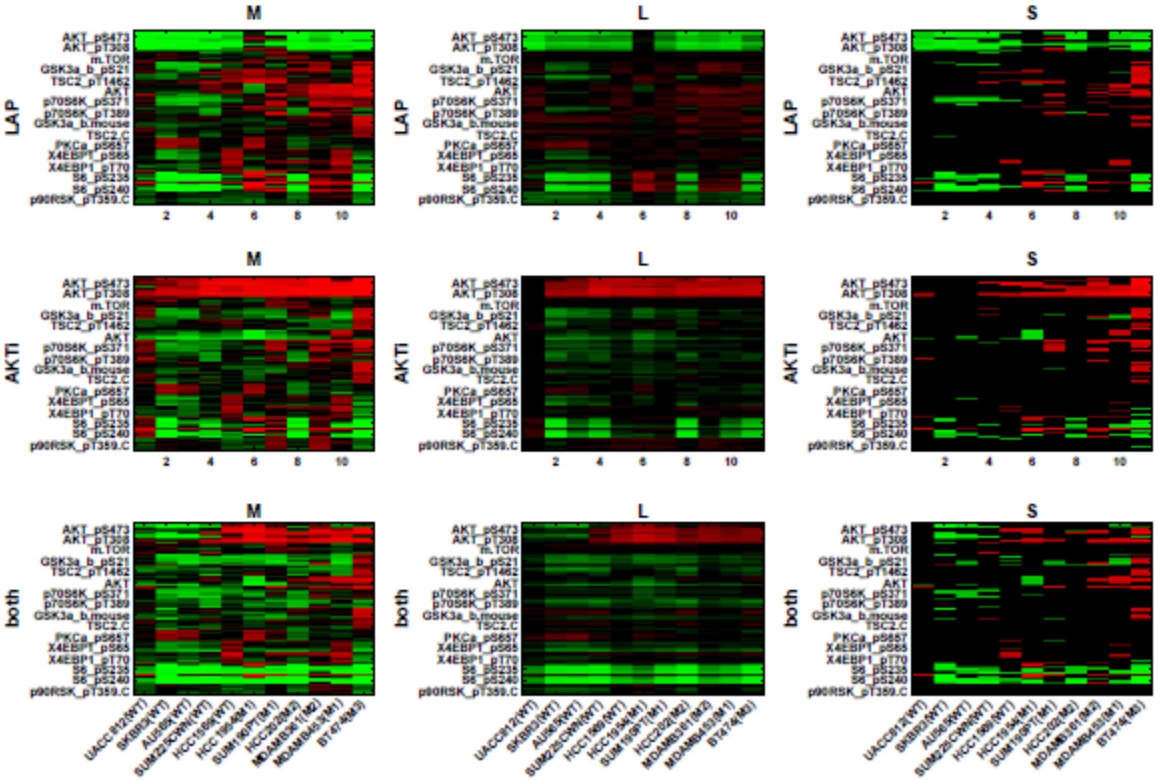
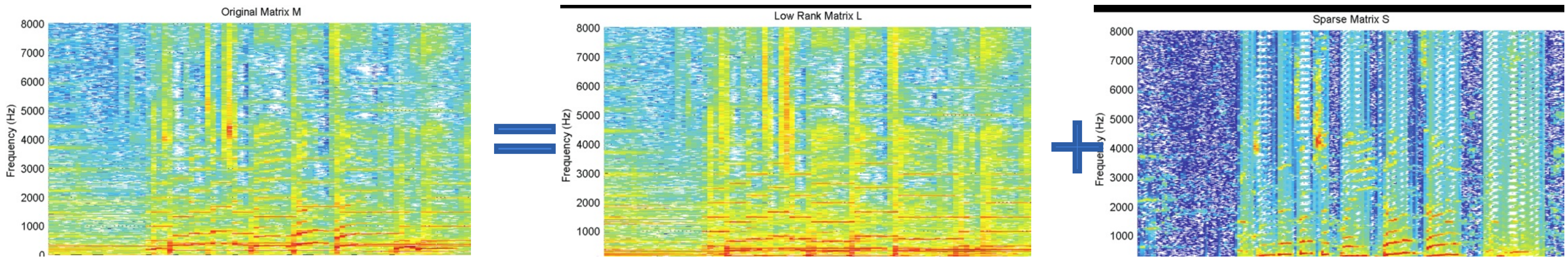


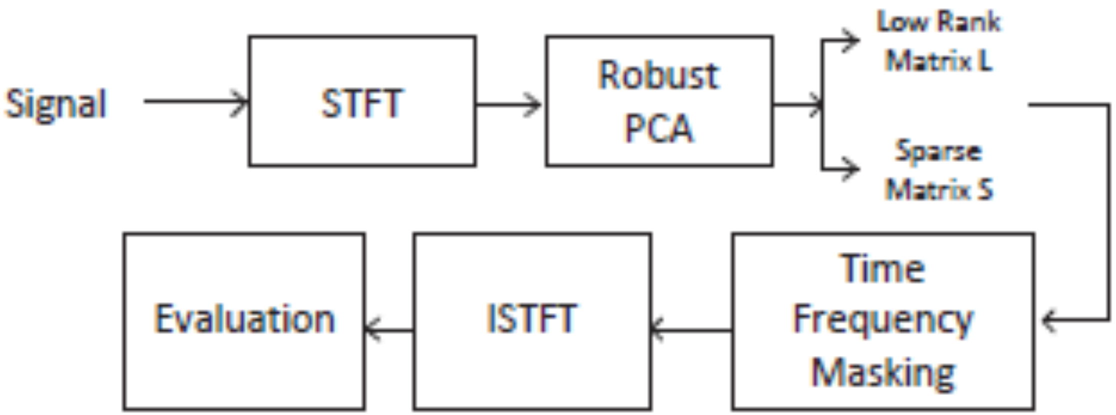
Figure S4. Separation result: (1_{st} column) raw data (2_{nd} column) low-rank component and (3_{rd} column) highly corrupted sparse component using threshold (M1: H1047R (kinase domain mutation) M2: E545K (helical domain mutation), and M3: K111N mutation in PIK3CA).

Chang, Korkola, Amin, Tomlin of Berkeley, BiorXiv, 2014.

Other Data/Applications: Lyrics and Music Separation

Songs (STFT) | Low-rank (music) | Sparse (voices)





Po-Sen Huang, Scott Chen, Paris Smaragdis, Mark Hasegawa-Johnson of UIUC, ICASSP 2012.

Other Data/Applications: Internet Traffic Anomalies

Network Traffic = Normal Traffic + Sparse Anomalies + Noise

$$D = L + RS + N$$

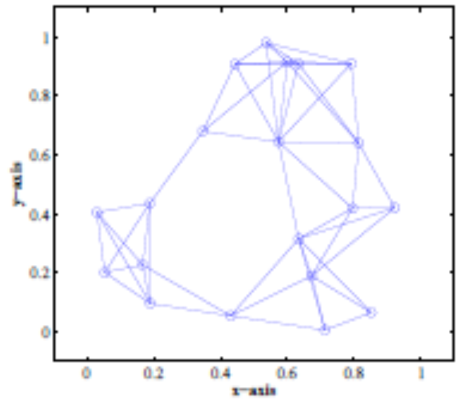
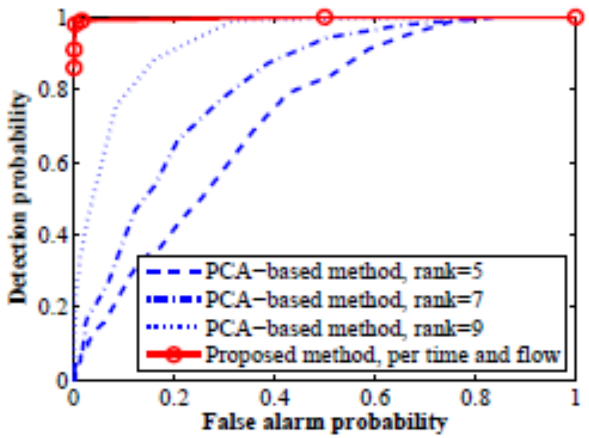
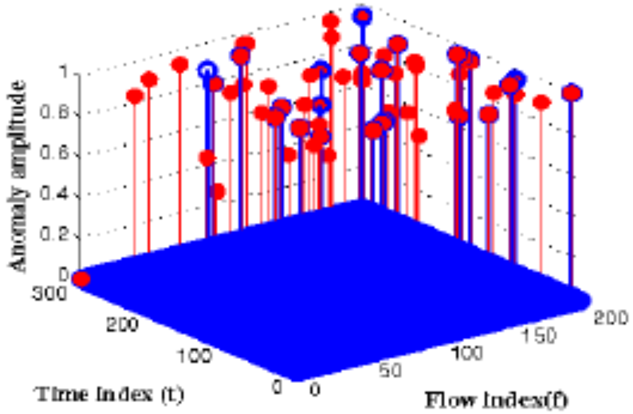


Fig. 2. Network topology graph.



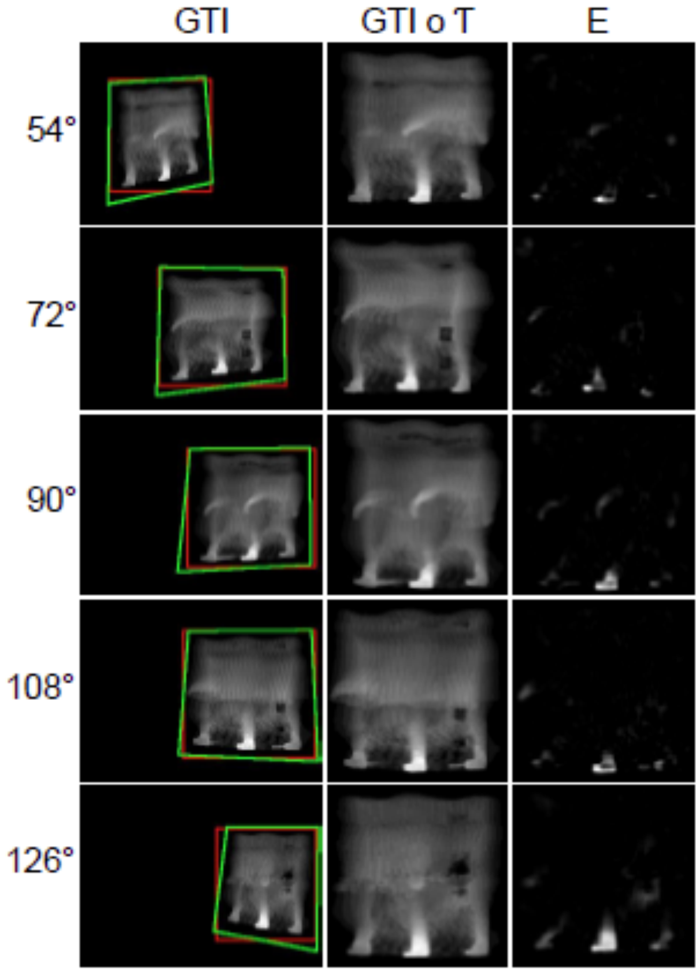


Mardani, Mateos, and Giannadis of Minnesota, Trans. Information Theory, 2013.

Other Data/pplications: View-Invariant Gait Recognition

Same gait from different views

Perspective distortion rectified



Kusakunniran et. al. of STU of Australia, IEEE Trans. on Info. Forensics & Security, 2013

Other Data/Applications: Robust Filtering and System ID

GPS on a Car:

$$\begin{cases} \dot{x} &= Ax + Bu, \quad A \in \Re^{r \times r} \\ y &= Cx + z + e \end{cases}$$

gross sparse errors
(due to buildings, trees…)

Robust Kalman Filter: $\hat{x}_{t+1} = Ax_t + K(y_t - C\hat{x}_t)$

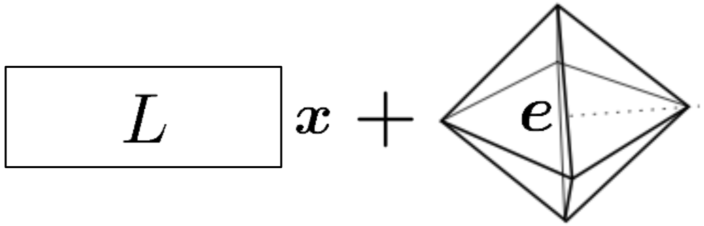
Robust System ID:

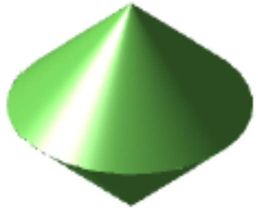
$$\underbrace{\begin{bmatrix} y_n & y_{n-1} & y_{n-2} & \cdots & y_0 \\ y_{n-1} & y_{n-2} & \cdots & \ddots & y_{-1} \\ y_{n-2} & \cdots & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & \ddots & y_{-n+2} \\ y_0 & y_{-1} & \cdots & y_{-n+2} & y_{-n+1} \end{bmatrix}}_{\text{Hankel matrix}} = \mathcal{O}_{n \times r} X_{r \times n} + S$$

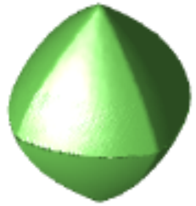
CONCLUSIONS – *A Unified Theory for Sparsity and Low-Rank*

	Sparse Vector	***Low-Rank Matrix***
Low-dimensionality of	individual signal	correlated signals
Measure	L_0 norm $\|x\|_0$	$\text{rank}(X)$
Convex Surrogate	L_1 norm $\|x\|_1$	Nuclear norm $\|X\|_*$
Compressed Sensing	$y = Ax$	$Y = A(X)$
Error Correction	$y = Ax + e$	$Y = A(X) + E$
Domain Transform	$y \circ \tau = Ax + e$	$Y \circ \tau = A(X) + E$
Mixed Structures	$Y = A(X) + B(E) + Z$	

Compressive Sensing of Low-Dimensional Structures







A norm $\|\cdot\|$ is said to be **decomposable** at $\boldsymbol{X}$ if there exists a subspace T and a matrix $\boldsymbol{S}$ such that

$$\partial\|\cdot\|(\boldsymbol{X}) = \{\Lambda \mid \mathcal{P}_T(\Lambda) = \boldsymbol{S}, \|P_{T^\perp}(\Lambda)\|^* \leq 1\},$$

where $\|\cdot\|^*$ is the dual norm of $\|\cdot\|$, and $\mathcal{P}_{T^\perp}$ is nonexpansive w.r.t. $\|\cdot\|^*$.

Theorem [Candes, Recht'11] Any low-complexity signal $\boldsymbol{X}^0$ can be exactly recovered from high compressive measurements via convex optimization:

$$||\boldsymbol{X}||_\diamond \quad \text{subject to} \quad \mathcal{P}_Q(\boldsymbol{X}) = \mathcal{P}_Q(\boldsymbol{X}^0),$$

for a decomposable norm $\|\cdot\|_\diamond$.

Compressive Sensing and Separation of Low-dim Structures

Suppose $(\boldsymbol{X}_1^0, \ldots, \boldsymbol{X}_k^0) = \arg\min \sum_{i=1}^k \lambda_i \|\boldsymbol{X}_i\|_{(i)}$ subj $\sum_{i=1}^k \boldsymbol{X}_i = \sum_{i=1}^k \boldsymbol{X}_i^0$, for decomposable norms $\|\cdot\|_{(i)}$ that majorize the Frobenius norm.

Theorem 6 (Compressive Sensing of Mixed Low-Comp. Structures). *Let $Q^\perp$ be a random subspac of $\mathbb{R}^{m\times n}$ of dimension*

$$\dim(Q) \geq O(\log^2 m) \times \text{intrinsic degrees of freedomof } (\boldsymbol{X}_1, \ldots, \boldsymbol{X}_k),$$

distributed according to the Haar measure, independent of $\boldsymbol{X}_i$. Then with very high probability

$$(\boldsymbol{X}_1^0, \ldots, \boldsymbol{X}_k^0) = \arg\min \sum_{i=1}^k \lambda_i \|\boldsymbol{X}_i\|_{(i)} \quad \text{subj} \quad \mathcal{P}_Q\Big[\sum_{i=1}^k \boldsymbol{X}_i\Big] = \mathcal{P}_Q\Big[\sum_{i=1}^k \boldsymbol{X}_i^0\Big],$$

and the minimizer is unique.

Extension to General Low-Dimensional Structures

Compressive Sensing:

$$\min \|\boldsymbol{X}\|_\diamond \quad \text{s.t.} \quad \mathcal{P}_Q(\boldsymbol{X}) = \mathcal{P}_Q(\boldsymbol{D})$$

Multiple-Structure Decomposition:

$$\min \textstyle\sum_i \lambda_i \|\boldsymbol{X}_i\|_{\diamond_i} \quad \text{s.t.} \quad \textstyle\sum_i \boldsymbol{X}_i = \boldsymbol{D}$$

Compressive Multiple-Structure Decomposition:

$$\min \textstyle\sum_i \lambda_i \|\boldsymbol{X}_i\|_{\diamond_i} \quad \text{s.t.} \quad \mathcal{P}_Q[\textstyle\sum_i \boldsymbol{X}_i] = \mathcal{P}_Q[\boldsymbol{D}]$$

Examples: **PCP** [CLMW'11], **outlier pursuit** [Xu+Caramanis+Sanghavi], **morphological component analysis** [Bobin et. al.], many more …

A Unified THEORY – *A Suite of Powerful Regularizers*

For compressive robust recovery of a family of low-dimensional structures:

- [Zhou et. al. '09] Spatially contiguous sparse errors via MRF
- [Bach '10] – relaxations from submodular functions
- [Negahban+Yu+Wainwright '10] – geometric analysis of recovery
- [Becker+Candès+Grant '10] – algorithmic templates
- [Xu+Caramanis+Sanghavi '11] column sparse errors $L_{2,1}$ norm
- [Recht+Parillo+Chandrasekaran+Wilsky '11'12] – compressive sensing of various structures
- [Candes+Recht '11] – compressive sensing of decomposable structures

$$X^0 = \arg\min \|X\|_\diamond \quad \text{s.t.} \quad \mathcal{P}_Q(X) = \mathcal{P}_Q(X^0)$$

- [McCoy+Tropp'11,Amenlunxen+McCoy+Tropp'13] – phase transition for recovery and decomposition of structures

$$(X_1^0, X_2^0) = \arg\min \|X_1\|_{(1)} + \lambda\|X_2\|_{(2)} \;\; \text{s.t.} \;\; X_1 + X_2 = X_1^0 + X_2^0$$

- [Wright+Ganesh+Min+Ma, ISIT'12,I&I'13] – compressive superposition of decomposable structures

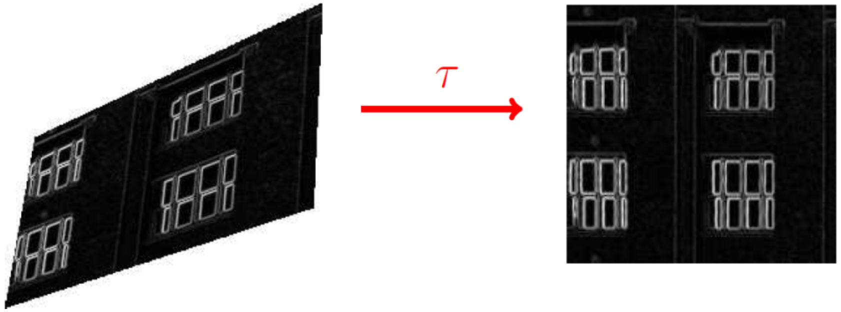
$$(X_1^0, \ldots, X_k^0) = \arg\min \textstyle\sum \lambda_i \|X_i\|_{(i)} \;\; \text{s.t.} \;\; \mathcal{P}_Q(\sum_i X_i) = \mathcal{P}_Q(\sum_i X_i^0)$$

Take home message: ***Let the data and application tell you the structure…***

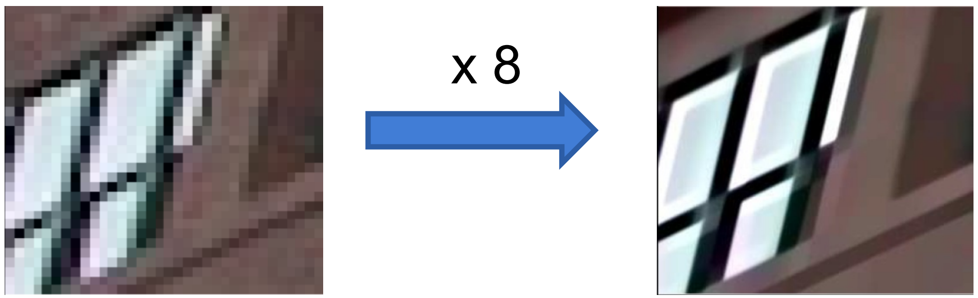
Super Resolution via Transform Invariant Group Sparsity

Aim: Exploiting non-local structures to perform super-resolution at large upsampling factors by

1. Learning the transformation that reveals the group-sparse structure of the image gradient (via TILT)

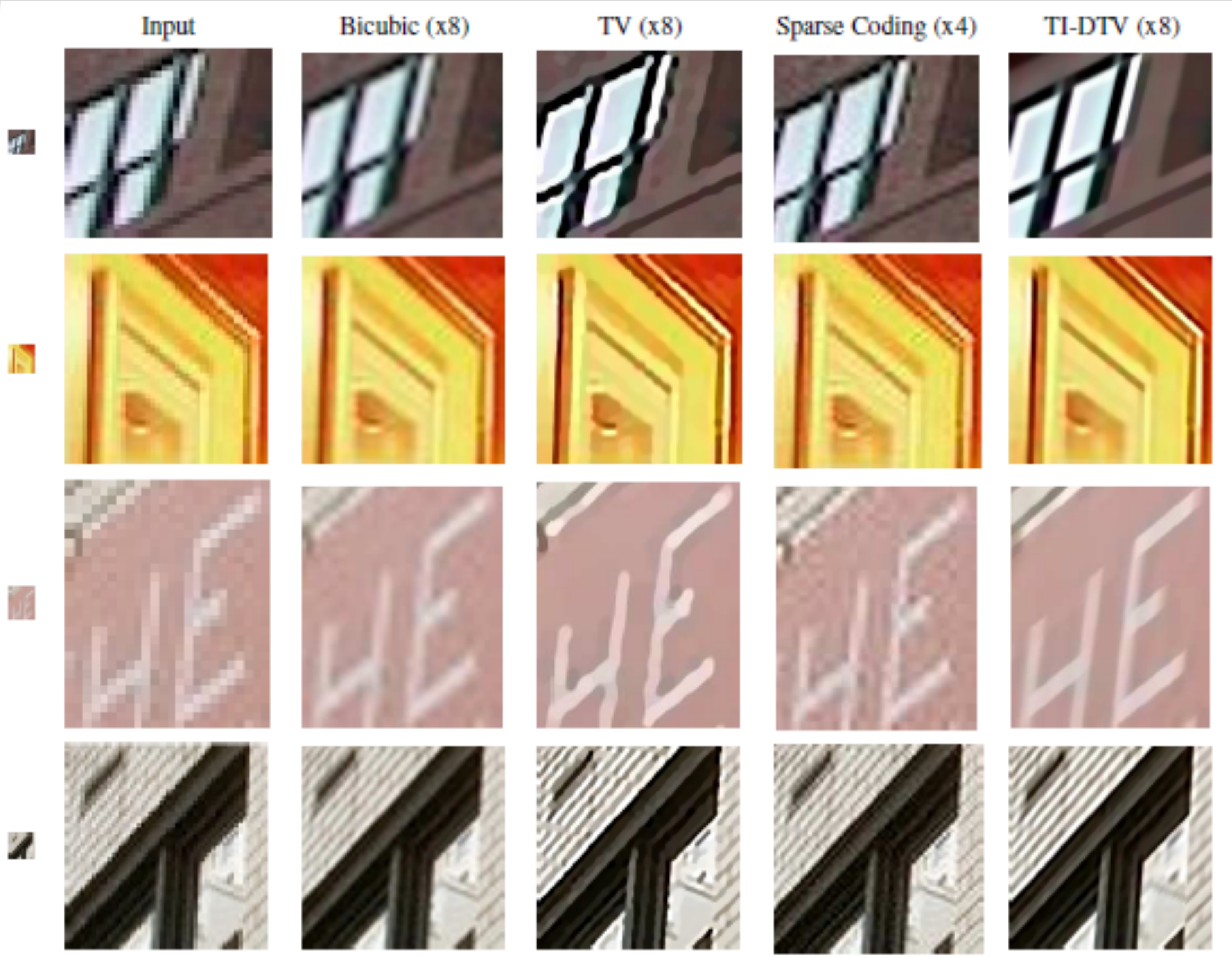


2. Enforcing this structure through group-sparse regularizers (DTV) that incorporates the transform and is consequently invariant to the transform



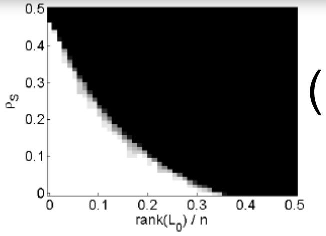
Carlos Fernandez and Emmanuel Candes of Stanford, ICCV2013

Super Resolution via Transform Invariant Group Sparsity



Carlos Fernandez and Emmanuel Candes of Stanford, ICCV2013

A Perfect Storm…



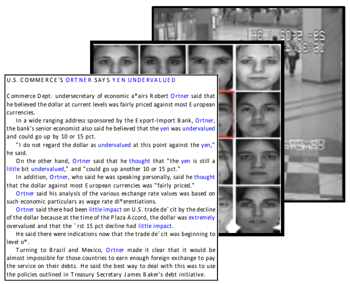
(a) Robust PCA, Random Signs

Mathematical Theory
(high-dimensional statistics, convex geometry
measure concentration, combinatorics…)

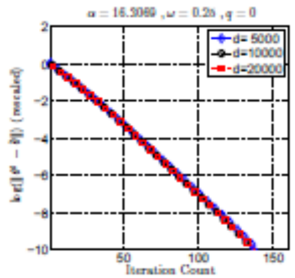
BIG DATA
(images, videos,
voices, texts,
biomedical, geospatial,
consumer data…)

Cloud Computing
(parallel, distributed,
scalable platforms)

Applications & Services
(data processing,
analysis, compression,
knowledge discovery,
search, recognition…)



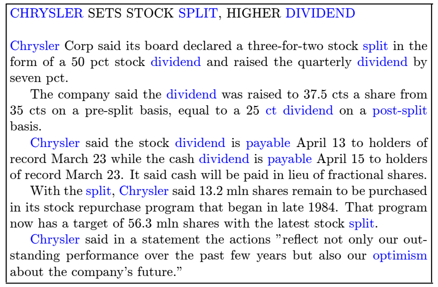
Computational Methods
(convex optimization, first-order algorithms
random sampling, approximate solutions…



A Perfect Storm…

Dr. Arvind Ganesh, vision architect of Baarzo.com
web video analysis
purchased by Google in June, 2014

Kerui Min, CTO of Bosonnlp.com
web document analysis,
found in Shanghai, 2013



CHRYSLER SETS STOCK SPLIT, HIGHER DIVIDEND

Chrysler Corp said its board declared a three-for-two stock split in the form of a 50 pct stock dividend and raised the quarterly dividend by seven pct.

The company said the dividend was raised to 37.5 cts a share from 35 cts on a pre-split basis, equal to a 25 ct dividend on a post-split basis.

Chrysler said the stock dividend is payable April 13 to holders of record March 23 while the cash dividend is payable April 15 to holders of record March 23. It said cash will be paid in lieu of fractional shares.

With the split, Chrysler said 13.2 mln shares remain to be purchased in its stock repurchase program that began in late 1984. That program now has a target of 56.3 mln shares with the latest stock split.

Chrysler said in a statement the actions "reflect not only our outstanding performance over the past few years but also our optimism about the company's future."

Dr. Allen Yang, CTO of Atheerlabs.com
stereo gargle, object & gesture recognition,
found on Google campus, 2012

REFERENCES + ACKNOWLEDGEMENT

Core References:

- *Robust Principal Component Analysis*? Candes, Li, Ma, Wright, Journal of the ACM, 2011.
- *TILT: Transform Invariant Low-rank Textures,* Zhang, Liang, Ganesh, and Ma, IJCV 2012.
- *Compressive Principal Component Pursuit*, Wright, Ganesh, Min, and Ma, IMA I&I 2013.

More references, codes, and applications on the website:

http://perception.csl.illinois.edu/matrix-rank/home.html

Colleagues:

- Prof. Emmanuel Candes (Stanford)
- Prof. John Wright (Columbia)
- Prof. Zhouchen Lin (Peking University)
- Dr. Yasuyuki Matsushita (MSRA)
- Dr. Arvind Ganesh (IBM Research, India)
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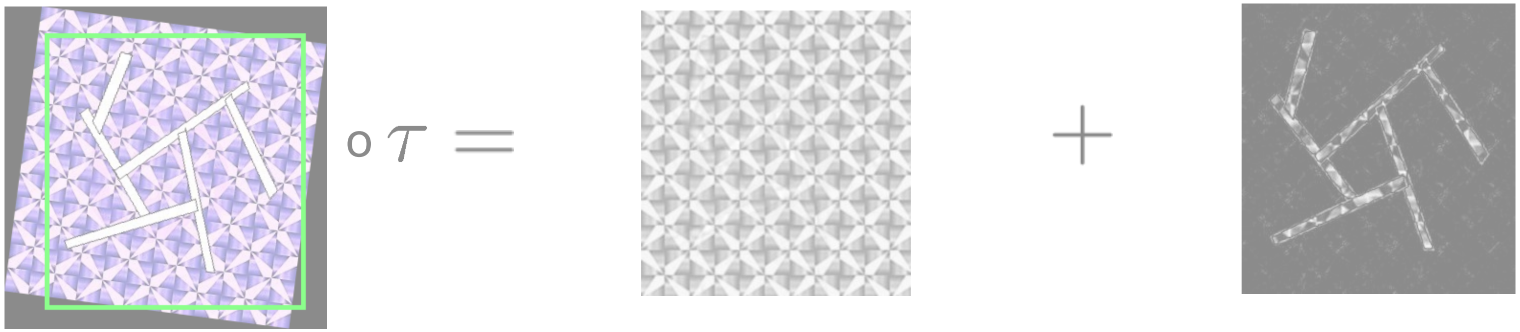
- Zhihan Zhou (UIUC, now PennState)
- Hossein Mobahi (UIUC, now MIT)
- Guangcan Liu (UIUC, now UPenn)
- Xiaodong Li (Stanford)
- Carlos Fernandez (Stanford, MSRA)

THANK YOU!

Questions, please?



$$D \circ \tau \;=\; A + E \qquad \min \;\; \|A\|_* + \lambda \|E\|_1$$