Differential Groups and the Gamma Function

Michael F. Singer

Department of Mathematics North Carolina State University Raleigh, NC 27695-8205 singer@math.ncsu.edu

> FoCM 2014 Montevideo, Uruguay 17 December 2014

Theorem: (Hölder, 1887) The Gamma function defined by

 $\Gamma(x+1) - x\Gamma(x) = 0$

satisfies no polynomial differential equation that is, there is no nonzero polynomial

 $P(x, y, y', y'', \dots, y^{(n)}) \in \mathbb{C}[x, y, y', \dots, y^{(n)}, \dots]$ such that $P(x, \Gamma(x), \Gamma'(x), \dots \Gamma^{(n)}(x)) = 0.$

Group Theory

\Downarrow Galois Theory

Form of Functional Dependencies

- Galois Theory of Linear Differential Equations
- Galois Theory of Linear Differential Equations with Continuous Parameters
- Galois Theory of Linear Difference Equations with Continuous Parameters
- Galois Theory of Linear Differential/Difference Equations with Discrete Parameters

Galois Theory of Polynomial Equations

$$P(y) = y^n + a_{n-1}y^{n-1} + \ldots + a_1y + a_0 = 0, \quad a_i \in \mathbb{Q}$$

Galois group = the group of transformations of the roots $\alpha_1, \ldots, \alpha_n$ that preserve all algebraic relations among them.

- Splitting Field $E = \mathbb{Q}(\alpha_1, \ldots, \alpha_n)$.
- Galois Group $Gal(E/\mathbb{Q}) = \{\sigma \mid \sigma = \mathbb{Q}\text{-autom. of } E\}.$

 $\forall \sigma \in \text{Gal}(E/\mathbb{Q}), \ \sigma(\alpha_i) \text{ is again a root of } P(y)$

 \Rightarrow Gal(E/\mathbb{Q}) \hookrightarrow Symm_n

- ► Galois Correspondence: Subgroups ⇔ Subfields
- Galois group measures the amount of interaction among the roots:

$$|\operatorname{Gal}(E/\mathbb{Q})| = [E : \mathbb{Q}]$$

Galois Theory of Linear Differential Equations

 e^x is not an algebraic function.

Picard-Vessiot (PV) Theory

$$\frac{dY}{dx} = A(x)Y \quad A \in \mathsf{M}_n(\mathbb{C}(x))$$

▶ Splitting Field: $Y = (y_{i,j})$, $y_{i,j}$ analytic near $x = x_0$, det $Y \neq 0$, $K = \mathbb{C}(x) \subset \mathbb{C}(x)(y_{1,1}, \dots, y_{n,n}) = E$, PV-Extension Note: *E* is closed under $\partial = \frac{d}{dx}$

▶ Galois Group $\operatorname{Gal}_{\partial}(E/K) = \{\sigma \mid \sigma = K \text{-autom. of } E, \sigma \partial = \partial \sigma \}$

$$\forall \sigma \in \operatorname{Gal}_{\partial}(E/K), \ \partial(\sigma Y) = A(\sigma Y) \Rightarrow \exists \ C_{\sigma} \in \operatorname{GL}_{n}(\mathbb{C}) \sigma Y = Y \cdot C_{\sigma}$$
$$\operatorname{Gal}_{\partial}(K/\mathbb{Q}) \hookrightarrow \operatorname{GL}_{n}(\mathbb{C})$$

- Gal_∂(E/K) ⊂ GL_n(ℂ) is Zariski closed, a linear algebraic group
- Galois Correspondence:

 $H^{\text{Zariski closed}} \subset \mathsf{Gal}_{\partial}(E/K) \Leftrightarrow F^{\text{Diff. field}, \ k \subset F \subset E}$

Measuring the amount of relations:

 $\dim_{\mathbb{C}} \operatorname{Gal}_{\partial}(E/K) = \operatorname{tr.} \operatorname{deg.}_{K} E$

e^x is not an algebraic function

$$\frac{dy}{dx} = y \qquad k = \mathbb{C}(x)$$

▶ PV-extension $E = k(e^x)$, $\operatorname{Gal}_{\partial}(E/k) \subset \operatorname{GL}_1(\mathbb{C}) = (\mathbb{C}^*, \times)$

- Closed subgps of $GL_1(\mathbb{C}) = \begin{cases} GL_1(\mathbb{C}) \\ \mathbb{Z}/n\mathbb{Z} = \{\zeta \mid \zeta^n = 1\}, n \in \mathbb{N}_{>0} \end{cases}$
- e^x algebraic over $\mathbb{C}(x) \Rightarrow \operatorname{Gal}_{\partial}(E/k) = \{\zeta \mid \zeta^n = 1\}$ for some *n*.
- e^x algebraic over $\mathbb{C}(x) \Rightarrow (e^x)^n \in \mathbb{C}(x)$ for some $n \in \mathbb{N}_{>0}$.
- e^x algebraic over $\mathbb{C}(x) \Rightarrow \frac{dz}{dx} = nz$ has a soln $z = e^{nx}$ in $\mathbb{C}(x)$.

$$z = c \prod (x - a_i)^{m_i} \Rightarrow n = \frac{dz/dx}{z} = \sum \frac{m_i}{x - a_i} \neq n.$$

 $\operatorname{Gal}_{\partial} = \{ \zeta \mid \zeta^n = 1 \} \Rightarrow y^n \in \mathbb{C}(x)$

Defining eqns. of group \Rightarrow Algebraic relations for solutions

More Examples

Ex.
$$\frac{dy}{dx} = \frac{t}{x}y$$
 $E = \mathbb{C}(x)(x^t)$
 $Gal(E/\mathbb{C}(x)) = \begin{cases} \mathbb{Z}/n\mathbb{Z} & \text{if } t = m/n, (m, n) = 1\\ \mathbb{C}^* = GL_1(\mathbb{C}) & \text{if } t \notin \mathbb{Q} \end{cases}$

Ex.
$$\frac{d^2y}{dx^2} - \frac{1}{x}\frac{dy}{dx} + (1 - \frac{\nu^2}{x^2})y = 0 \quad E = \mathbb{C}(x)(Y_{\nu}, Y'_{\nu}, J_{\nu}, J'_{\nu})$$
$$Gal(E/K) = SL_2(\mathbb{C}) \Leftrightarrow \nu \notin \mathbb{Z} + \frac{1}{2}$$
$$\dim_{\mathbb{C}} SL_2(\mathbb{C}) = 3 \Rightarrow \text{tr. } \deg_{\mathbb{C}(x)}E = 3$$
$$Y_{\nu}J'_{\nu} - Y'_{\nu}J_{\nu} = \frac{\pi}{x} \quad \text{and} \quad Y_{\nu}, Y'_{\nu}, J_{\nu} \text{ alg. indep. over } \mathbb{C}(x).$$

Galois Theory of Linear Differential Equations with Continuous Parameter

$$\partial_x Y = A(t,x)Y \quad A \in M_n(\mathbb{C}(t,x)), \quad \partial_x = \frac{\partial}{\partial x}$$

Galois group = the group of transformations of *Y* that preserve all algebraic relations among *x*, *Y*, and the $\{\partial_x, \partial_t\}$ -derivatives of *Y*.

$$\partial_t$$
-PV-Extension: $Y = (y_{i,j}), y_{i,j}$ analytic near $(t_0, x_0), \det Y \neq 0,$
 $K = \mathbb{C}(t, x) \subset \mathbb{C}(t, x)(y_{1,1}, \dots, y_{n,n}, \partial_t y_{1,1}, \dots, \partial_t^r \partial_x^s y_{i,j,\dots}) = E$

$$\partial_{t}\text{-}\mathsf{Gal}(E/K) = \{\sigma \mid \sigma = k\text{-}\mathsf{autom.}, \sigma \partial = \partial \sigma \ \partial \in \{\partial_{x}, \partial_{t}\}\}$$
$$\forall \sigma \in \partial_{t}\text{-}\mathsf{Gal}(E/K), \exists C_{\sigma} \in \mathsf{GL}_{n}(\mathbb{C}(t)) \text{ s. t. } \sigma Y = Y \cdot C_{\sigma}$$
$$\partial_{t}\text{-}\mathsf{Gal}(E/K) \hookrightarrow \mathsf{GL}_{n}(\mathbb{C}(t))$$

Ex.
$$\frac{\partial y}{\partial x} = \frac{t}{x}y$$
, $K = \mathbb{C}(x, t), \{\partial_x = \frac{\partial}{\partial x}, \partial_t = \frac{\partial}{\partial t}\}$

$$\partial_t - \mathsf{PV} - \mathsf{Ext.} = E = \mathbb{C}(x)(x^t, \partial_t(x^t), \ldots) = \mathbb{C}(x, x^t, \log x)$$
$$\partial_t - \mathsf{Gal}(E/\mathbb{C}(x, t)) = G = \{c \in \mathbb{C}(t)^* \mid \partial_t(\frac{\partial_t c}{c}) = 0\}$$

G is a Linear Differential Algebraic Group, a group of matrices whose entries satisfy a system of differential equations.

$$\partial_t(\frac{\partial_t c}{c}) = 0 \quad \Rightarrow \quad c(t) = ae^{bt}, \quad a, b \in \mathbb{C}$$

If $c(t) \in \mathbb{C}(t)$ then $c(t) = a \in \mathbb{C}!$ Need more functions of *t*.

Replace $\mathbb{C}(t)$ with a "large" field k of meromorphic functions of t.

Parameterized PV-Theory for Differential Eqns

Cassidy/Singer 2006

k = a sufficiently large field of functions of tK = k(x) with derivations ∂_x, ∂_t .

$$\partial_{\mathbf{x}} \mathbf{Y} = \mathbf{A}(\mathbf{x}, t) \mathbf{Y}, \quad \mathbf{A} \in \mathsf{M}_n(\mathbf{k}(\mathbf{x}, t))$$

One then has:

- Parameterized PV-extension $E = K(Y, \partial_t(Y), \partial_t^2(Y), ...)$
- Parameterized PV-Galois group G = Aut_{∂x,∂t}(E) linear differential algebraic group
- Galois Correspondence: differential subfields ↔ closed subgroups
- ► The size of *G* measures the amount of differential dependence defining differential equations for $G \Rightarrow \partial_t$ -differential relations among solutions

Linear Differential Algebraic Groups (LDAGs)

k - a ∂_t -differential field, $C = k^{\partial_t}$ = constants in *k*.

 $G \subset \operatorname{GL}_n(k)$, entries satisfy algebraic DEs with respect to t

Any Linear Algebraic Group and the constant pts of such a group.
eg, SL_n(C) ⊂ SL_n(k)
G ⊊ G_a(k₀) = (k, +) = { (1 α 0 1) | α ∈ k } ⇒ G = {α | L(α) = 0} where L ∈ k[∂/∂t]

$$G \subsetneq \mathbb{G}_m(k) = (k^*, \times) = \operatorname{GL}_1(k)$$

$$\Rightarrow G = \begin{cases} \mathbb{Z}/n\mathbb{Z} \\ \{\alpha \neq 0 \mid L(\frac{\partial_t(\alpha)}{\alpha}) = 0\} \text{ where } L \in k[\frac{\partial}{\partial t}] \end{cases}$$

$$\ell \partial_t : \mathbb{G}_m \to \mathbb{G}_a \quad z \mapsto \frac{\partial_t z}{z}$$

Ex. The Incomplete Gamma Function:

$$\gamma(t,x) = \int_0^x s^{t-1} e^{-s} ds$$

satisfies

$$\frac{\partial^2 \gamma}{\partial x^2} - \frac{t - 1 - x}{x} \frac{\partial \gamma}{\partial x} = 0$$

but satisfies no differential equation of the form

$$p(x, t, \gamma, \gamma_t, \gamma_{tt}, \ldots) = 0.$$

• Algorithms for 2nd order param. LDE - Dreyfus 2012, Arreche 2013

• Partial Algorithms for *n*th order - Minchenko/Ovchinnikov/Singer 2014

Ex. Integrable Systems/Isomonodromy:

Def. The system

$$\frac{\partial Y}{\partial x} = A(x,t)Y, \quad A(x,t) \in \mathsf{M}_n(\mathbb{C}(x,t))$$

is integrable if $\exists B(x, t) \in \mathbb{C}(x, t)$ such that

$$A_t - B_x = AB - BA.$$

i.e., if the systems $\frac{\partial Y}{\partial x} = A(x, t)Y$, $\frac{\partial Y}{\partial t} = B(x, t)Y$ are consistent.

Thm. A parameterized system is integrable if and only if its parameterized PV-group is conjugate to a group of <u>constant</u> matrices.

The param. PV-Group measures how far a system is from integrable.

Thm. (Mitschi-Singer, 2013) The Darboux-Halphen V system is associated with a projectively integrable system.

Galois Theory of Linear Difference Equations with Continuous Parameter

Hardouin/Singer 2008

Ex. Hermite polynomials:

$$H(n,t) = n! \sum_{m=0}^{\lfloor n/2 \rfloor} \frac{(-1)^m (2t)^{n-2m}}{m! (n-2m)!}$$

If $Y(n, t) = (H(n, t), H(n + 1, t))^T$, then

$$Y(n+1,t) = \begin{pmatrix} 0 & 1 \\ -2n & 2t \end{pmatrix} Y(n,t)$$

Is there a differential dependence on t? What is it?

$$\frac{\partial Y(n,t)}{\partial t} = \begin{pmatrix} 2t & -1 \\ 2n & 0 \end{pmatrix} Y(n,t).$$

Ex. Gamma Function:

$$\Gamma(x+1) = x\Gamma(x)$$

 $\Gamma(x)$ is a meromorphic function of *x*.

What are the differential properties of Γ ?

Algebraic Setting

K = a field with automorphism σ and derivation ∂ such that $\sigma \partial = \partial \sigma$. = a $\sigma \partial$ -field

Ex.
$$K = \mathbb{C}(x, t)$$

$$\begin{cases} \sigma(x) = x + 1 & \sigma(t) = t \\ \partial(x) = 0 & \partial(t) = 1 \end{cases} \quad \text{or} \quad \begin{cases} \sigma(x) = qx & \sigma(t) = t \\ \partial(x) = 0 & \partial(t) = 1 \end{cases}$$
Ex. $K = \mathbb{C}(x)$

$$\begin{cases} \sigma(x) = x + 1 \\ \partial(x) = 1 \end{cases} \quad \text{or} \quad \begin{cases} \sigma(x) = qx \\ \partial(x) = x \end{cases}$$

Given

$$\sigma(Y) = AY, \quad A \in \operatorname{GL}_n(K)$$

describe the behavior of solutions with respect to ∂ .

Parameterized PV-Theory for Difference Eqns

 $K = a \sigma \partial$ -field

$$\sigma(Y) = AY, \quad A \in \mathsf{M}_n(K)$$

One then has:

- Parameterized PV-extension E
- ▶ Parameterized PV-Galois group $Gal_{\sigma\partial}(E/K) = Aut_{\sigma\partial}(E/K)$

- linear differential algebraic group

- Galois Correspondence
- > The size of G measures the amount of differential dependence

defining differential equations for $G \Rightarrow \partial$ -differential relations among solutions

Ex. Gamma Function:

 $\Gamma(x+1) = x\Gamma(x)$

- Galois Group ⊂ GL₁
- ▶ Differential Subgroups of $GL_1 = \begin{cases} \{\zeta \mid \zeta^n = 1\}, \text{ or } \\ \{c \mid L(\frac{c'}{c}) = 0\} \end{cases}$
- Galois Theory $\Rightarrow L(\frac{\Gamma'(x)}{\Gamma(x)}) = g(x) \in \mathbb{C}(x)$
- Can assume L has constant coefficients, apply the shift σ and subtract:

$$L(\frac{1}{x}) = g(x+1) - g(x)$$

- $L(\frac{1}{x})$ has exactly one pole
- g(x + 1) g(x) has at least two poles

Ex. First order *q*-difference equations:

Thm:(Ishizaki, 1998) If $a(x), b(x) \in \mathbb{C}(x)$ and $z(x) \notin \mathbb{C}(x)$ satisfies

$$z(qx) = a(x)z(x) + b(x), |q| \neq 1$$
 (1)

and is meromorphic on $\underline{\mathbb{C}}$, then z(x) is not differentially algebraic over *q*-periodic functions.

z(x) meromorphic on $\mathbb{C} \setminus \{0\}$ and satisfies (1):

Assume distinct zeroes and poles of a(x) are not q-multiples of each other.

Thm: (H-S) z(x) is differentially algebraic iff $a(x) = cx^n$ and

▶
$$b = f(qx) - a(x)f(x)$$
 for some $f \in \mathbb{C}(x)$, when $a \neq q^r$, or

▶ $b = f(qx) - af(x) + dx^r$ for some $f \in \mathbb{C}(x), d \in \mathbb{C}$ when $a = q^r, r \in \mathbb{Z}$.

Ex. q-Hypergeometric Functions:

Thm: (Roques, 2007) Let $y_1(x)$, $y_2(x)$ be lin. indep. solutions of

$$y(q^{2}x) - \frac{2ax - 2}{a^{2}x - 1}y(qx) + \frac{x - 1}{a^{2}x - q^{2}}y(x) = 0$$
 (2)

with $a \notin q^{\mathbb{Z}}$ and $a^2 \in q^{\mathbb{Z}}$. Then $y_1(x), y_2(x), y_1(qx)$ are algebraically independent.

(Hardouin/Singer): $y_1(x)$, $y_2(x)$, $y_1(qx)$ are differentially independent.

In general, we give necessary and sufficient *computable* conditions for a large class of linear difference equations for differential dependence of solutions and give differential relations if these are differentially dependent.

Other recurrences

The series

$$B(x) = \sum_{n=0}^{\infty} B_n x^n = 1 + x + 2x^2 + 5x^3 + 15x^4 + \dots$$

$$B_n = \text{ no. of ways to partition } \{1, 2, \dots, n\} = \text{Bell numbers}$$

$$B(\frac{x}{1+x}) - xB(x) = 1$$

$$M(x) = \sum_{n=0}^{\infty} x^{k^n}, \quad k \ge 2, \quad \text{Mahler function}$$

$$M(x^k) - M(x) = x$$

are not differentially algebraic.

Galois Theory of Linear Differential Equations with Discrete Parameters Hardouin/Di Vizio/Wibmer 2014

Galois groups are Difference Groups.

Ex. $K = \mathbb{C}(x, \alpha), \ \delta = \frac{d}{dx}, \ \sigma(\alpha) = \alpha + 1$. The Bessel function $J_{\alpha}(x)$ satisfies

$$x^2\frac{d^2y}{dx^2} + x\frac{dy}{dx} + (x^2 - \alpha^2)y = 0$$

How does J_{α} depend on α ?

$$xJ_{\alpha+2}(x)-2(\alpha+1)J_{\alpha+1}(x)+xJ_{\alpha}(x)=0.$$

Ex. $K = \mathbb{C}(x)$, $\delta = \frac{d}{dx}$, $\sigma(x) = x + 1$. Ai(x),Bi(x) are lin. indep. solns. of

$$\frac{d^2y}{dx^2} - xy = 0$$

then Ai(x), Bi(x), $\frac{dAi(x)}{dx}$, Ai(x + 1), Bi(x + 1), $\frac{dAi(x+1)}{dx}$, ... are alg. ind. over $\mathbb{C}(x)$.

Galois Theory of Linear Difference Equations with Discrete Parameters

Ovchinnikov/Wibmer 2014

Galois groups are Difference Groups.

Thm: The Gamma Function satisfies no difference equation with respect to $x \mapsto x + c, c \notin \mathbb{Q}$ over $M_{<1}$, the field of meromorphic functions *f* whose Nevanlinna characteristic satisfies T(f, r) = o(r).